



( $u_i > 0$ ) or solutions with non-physical oscillations in the  $u_i$ . Conclude that the difference scheme produces no oscillations, if  $c \leq 0$ .

(d) For the central scheme, we have  $c = -1 + \frac{P_e \Delta x}{2}$  and  $P_e \Delta x \leq 2$ , whereas for the upwind scheme  $c = -1$  (unconditionally).

Show, by using Taylor series, that the (local) truncation error for the upwind scheme is  $\mathcal{O}(\Delta x)$  (for the original model), but  $\mathcal{O}((\Delta x)^2)$  for the so-called modified equation:

$$\left(-\delta + \frac{\nu \Delta x}{2}\right)u''(x) + \nu u'(x) = 0,$$

where  $\frac{\nu \Delta x}{2}$  is a numerical (artificial) diffusion coefficient.

(e) Plot a few relevant numerical solutions (choose specific values for  $P_e$ ) to support the results from parts (a)-(d). Also compare the results with the exact solution of the model. Discuss the numerical solutions in terms of (unphysical) oscillations and (extra) damping.

## PART B (10 points)

(a) Construct a time-integration method for  $y'(t) = f(y(t))$  that is consistent, but not zero-stable<sup>2</sup>.

(b) Determine and plot the stability region in the complex plane of the following linear multistep method:

$$y^{n+2} - y^{n+1} = \Delta t f(y^n).$$

## PART C (30 points)

Consider the heat equation

$$\frac{\partial u}{\partial t} = \frac{1}{6} \frac{\partial^2 u}{\partial x^2}, \quad x \in [0, 1], \quad t \in (0, T],$$

with initial /boundary conditions  $u(x, 0) = \sin(\pi x)$ ,  $u(0, t) = 0$ ,  $u(1, t) = 0$ . The exact solution reads  $u(x, t) = e^{-\frac{\pi^2}{6}t} \sin(\pi x)$ .

(a) Write a *computercode* (in Matlab or Python) for the FTCS-scheme when applied to this model. In this code  $\Delta x$  and  $\Delta t$  are input parameters.

(b) Make a table of the maximum (absolute) error at  $T = 0.6$  as a function of  $\Delta t$  ( $= 10^{-2}, 10^{-3}, \dots, 10^{-5}$ ) and  $\Delta x$  ( $= \frac{1}{5}, \frac{1}{10}, \dots, \frac{1}{80}$ ). Is the method *stable* for each combination of  $\Delta t$  and  $\Delta x$ ?

<sup>2</sup>It is not allowed to use the examples that are discussed in the exercises or lecture notes.

(c) Make a few relevant plots as an illustration of the numerical experiments (don't forget to plot the exact solution as well).

(d) Explain your numerical results in terms of accuracy and stability.

(e) Next, take the special ratio  $\frac{\Delta t}{(\Delta x)^2} = 1$  and  $\Delta t = 10^{-2}, \dots, 10^{-4}$ . What happens with the maximum absolute error as a function of  $\Delta t$ ? Can you explain this theoretically?

(f) Send the Matlab (or Python) code(s) to: P.A.Zegeling@uu.nl.

## PART D (40 points)

In phase-field theory the propagation of domain walls in liquid crystals may be modelled by the following *sixth*-order time-dependent PDE model:

$$\frac{\partial u}{\partial t} = \delta \frac{\partial^6 u}{\partial x^6} + \gamma \frac{\partial^4 u}{\partial x^4} + \epsilon \frac{\partial^2 u}{\partial x^2} + u - u^3 \quad (2)$$

with  $\epsilon, \delta, \gamma \in \mathbb{R}$ ,  $x \in [0, L]$ ,  $t \in [0, T]$  and initial condition  $u(x, 0) = u_0(x)$ .

We consider three special cases<sup>3</sup>:

### Case I (Fisher/Huxley)

$\delta = \gamma = 0$ ,  $\epsilon = 1$ ,  $L = 100$ ,  $T = 30$ ,  $u_0(x) = e^{-\frac{x^2}{16}}$ ,  $u(0, t) = 1$ ,  $u(L, t) = 0$ .  
("a monotone travelling wave solution")

### Case II (extended Fisher-Kolmogorov)

$\delta = 0$ ,  $\gamma = -1$ ,  $\epsilon = -2$ ,  $L = 100$ ,  $T = 10$ ,  $u_0(x) = \cos(\frac{\pi x}{20})$ ,  $u(0, t) = 1$ ,  $u_x(0, t) = 0$ ,  $u(L, t) = -1$ ,  $u_x(L, t) = 0$ .  
("Batman-ear" solutions)

### Case III (pattern formation in phase transitions)

$\delta = 0.12$ ,  $\gamma = -0.5$ ,  $\epsilon = 1$ ,  $L = 300$ ,  $T = 120$ ,  $u_0(x) = e^{-\frac{x^2}{16}}$ ,  $u(0, t) = 1$ ,  $u_x(0, t) = 0$ ,  $u_{xx}(0, t) = 0$ ,  $u(L, t) = 0$ ,  $u_x(L, t) = 0$ ,  $u_{xx}(L, t) = 0$ .  
("travelling oscillatory waves")

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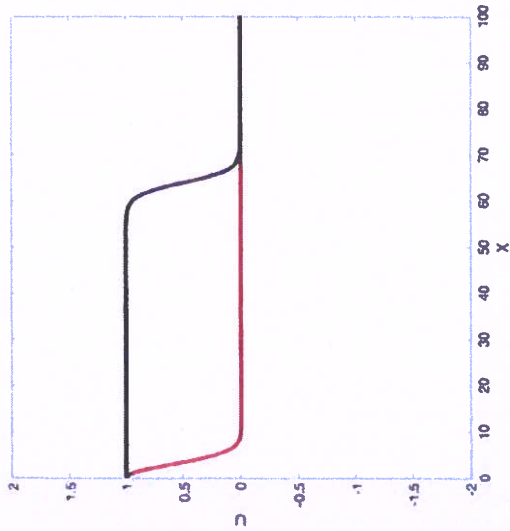
<sup>3</sup>You need to pay extra attention to the boundary conditions!

- (a) First, numerically approximate the spatial derivatives in model (2).
- (b) Then, apply an explicit time-integration method (EF, RK2, RK4, ...) or a standard time-integrator of Matlab or Python.
- (c) Motivate the validity of your results qualitatively. (check the accuracy and explain!)<sup>4</sup>
- (d) Illustrate your report with graphs at  $t = 0$  and  $t = T$ .
- (e) Send the Matlab (or Python) code(s) to: P.A.Zegeling@uu.nl.

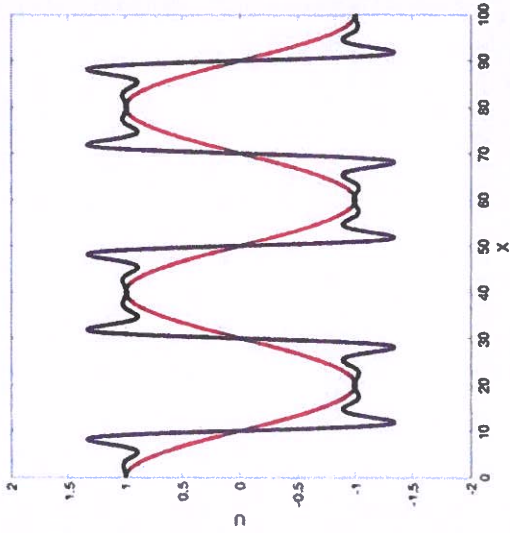
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<sup>4</sup>You may consult the next page for accurately computed solutions.

Case I



Case II



Case III

