## Book: Dynamical Oceanography Author: Dijkstra, H. A.; email: H.A.Dijkstra@uu.nl Chapter: 3, Exercise: 3.2: Properties of the Coriolis acceleration Version: 1

a. Show, in the same way as in section 3.1.2, that the rotation of the  $(\mathbf{e}_1, \mathbf{e}_3)$  plane induces an acceleration  $-2\Omega w \cos \theta$  in the  $\mathbf{e}_1$  direction and an acceleration  $2\Omega u \cos \theta$  in the  $\mathbf{e}_3$  direction.

The vertical plane spanned by  $e_1$  and  $e_3$  rotates clockwise with angular velocity  $\Omega \cos \theta$ . Consider the movement of fluid parcels in the plane  $(e_1, e_3)$ . Within a time  $\Delta t$  the coordinate system  $(e_1, e_3)$ rotates over an angle  $\Delta t\Omega \cos \theta$ . A parcel which moves at t = 0 uniformly along  $e_3$  with velocity warrives after  $\Delta t$  in point A, with  $|OA| = w\Delta t$ . With respect to the rotating coordinate system, the parcel will have an displacement (in the negative  $e_1$  direction):  $-w(\Delta t)^2\Omega \cos \theta$ . The acceleration is uniform in the negative direction of  $e_1$  and when denoted by  $a_1^c$ , the displacement can be written as  $\frac{1}{2}a_1^c(\Delta t)^2$ . From the last two relations it follows that  $a_1^c = -2\Omega w \cos \theta$  in the  $e_1$ .

In the same way, an expression can be derived for the component of the apparent acceleration in the direction of  $e_3$ . A fluid parcel which moves uniformly in the  $e_1$  direction with velocity u is displaced with respect to the rotation coordinate system, in  $\Delta t$ , in the positive  $e_3$  direction. In the same way as before, it follows that the displacement is  $u(\Delta t)^2 \Omega \cos \theta$  and  $a_3^c = 2\Omega u \cos \theta$  in the  $e_3$  direction.

In section 3.1.2 we derived the expression for the Coriolis acceleration  $\vec{a}^c$ .

b. Show that  $\vec{a}^c \perp \vec{\Omega}$  and  $\vec{a}^c \perp \vec{v}$ .

As  $\vec{a}^c = -2\vec{\Omega} \wedge \vec{v}$ , the acceleration vector is orthogonal to  $\vec{\Omega}$  and  $\vec{v}$ . This can also be shown by using the scalar product of vectors. For example, given that  $\vec{a_c} = (2\Omega(v\sin\theta - w\cos\theta), -2\Omega u\sin\theta, 2\Omega u\cos\theta)$  and  $\vec{v} = (u, v, w)$  it results that  $\vec{a_c} \cdot \vec{v} = 2\Omega u(v\sin\theta - w\cos\theta) - 2v\Omega u\sin\theta + w2\Omega u\cos\theta = 0$ . Therefore,  $\vec{a_c} \perp \vec{v}$ .