

## INLDS Practicum 8

For each planar system below, construct its phase portrait for  $\alpha = 0$  and for small  $\alpha < 0$  and  $\alpha > 0$  using the MATLAB tool `pplane9`. Identify the occurring bifurcation and try to support your conclusions by analytical arguments as outlined below.

### Exercises

#### Ex.1 A system with a global bifurcation

$$\begin{cases} \dot{x} &= 1 - x^2 - \alpha xy, \\ \dot{y} &= xy + \alpha(1 - x^2). \end{cases} \quad (1)$$

Prove that for  $\alpha = 0$  there exists a heteroclinic connection between two saddles.

- Determine the equilibria and classify them.
- Compute the heteroclinic solution explicitly and verify the limits  $t \rightarrow \pm\infty$ .

#### Ex.2 A system with a saddle homoclinic bifurcation

$$\begin{cases} \dot{x} &= -x + 2y + x^2, \\ \dot{y} &= (2 - \alpha)x - y - 3x^2 + \frac{3}{2}xy. \end{cases} \quad (2)$$

Recall that for  $\alpha = 0$  the system has a homoclinic orbit with  $\sigma < 0$ .

- Predict the stability of the bifurcating cycle and the direction of its bifurcation.
- Challenge:** Show that the splitting function  $\beta(\alpha)$  has a regular zero at  $\alpha = 0$ , see Theorem 4.4 in *Applied Nonlinear Dynamics*.

#### Ex.3 A system with a fold bifurcation of a cycle

$$\begin{cases} \dot{x} &= (\alpha - \frac{1}{4})x - y + x(x^2 + y^2) - x(x^2 + y^2)^2, \\ \dot{y} &= x + (\alpha - \frac{1}{4})y + y(x^2 + y^2) - y(x^2 + y^2)^2. \end{cases} \quad (3)$$

- Introduce polar coordinates  $x = r \cos \varphi$ ,  $y = r \sin \varphi$ .
- Analyze the number and stability of equilibria of the  $r$ -equation for various  $\alpha$ . Plot the equilibria (horizontally) versus  $\alpha$  (vertically).
- Show that  $\alpha = 0$  the system (3) has a non-hyperbolic cycle, so that a fold bifurcation of cycles should occur in the system.
- Challenge:** Compute the quadratic normal form coefficient for the fold bifurcation. *Hints:* Apply separation of variables to  $\dot{r} = r(\alpha - \frac{1}{4} + r^2 - r^4)$  to define a suitable function  $g$  such that  $g(r_0, r_1) = 0$ , where  $r_0 = r(0)$  and  $r_1 = r(2\pi)$ . Introduce the Poincaré map  $P(r_0) = r_1$  and differentiate the relation  $g(r_0, P(r_0)) = 0$  twice with respect to  $r_0$  to get the second derivative of  $P$  at the critical fixed point  $r_0 = \frac{1}{\sqrt{2}}$ . Use limit values of the derivatives.

### Homework

Hand-in is exercise 3.