## Exercise 0.1. Define

$$g: \mathbf{R}^3 \to \mathbf{R}$$
 by  $g(x) = x_1^2 + x_2^2 - (1 - x_3)x_3^2$  and  $V = \{x \in \mathbf{R}^3 \mid g(x) = 0\}.$ 

(i) Verify that  $V \subset \{x \in \mathbf{R}^3 \mid x_3 \le 1\}$ .

Given an arbitrary point  $x \in V$ , the result in (i) suggests to write  $x_3 = 1 - s^2$  for some  $s \in \mathbf{R}$ .

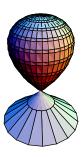
(ii) Conclude

$$V \subset \operatorname{im}(\phi)$$
 with  $\phi : \mathbf{R}^2 \to \mathbf{R}^3$  given by  $\phi(s, t) = (1 - s^2)(s \cos t, s \sin t, 1)$ .  
Show that actually one has  $V = \operatorname{im}(\phi)$ .

(iii) Demonstrate that  $\phi$  is an immersion at all points of  $\mathbb{R}^2$  with the exception of the points  $(\pm 1, t)$  and (0, t), for arbitrary  $t \in \mathbb{R}$ . More precisely, prove

$$\dim \ker (D\phi(\pm 1, t)) = \dim \ker (D\phi(0, t)) = 1.$$

Verify 
$$\phi(\pm 1, t) = 0$$
 and  $\phi(0, t) = (0, 0, 1) = n$ , for all  $t \in \mathbf{R}$ .



## Illustration for Exercise 0.1

In the illustration we note nothing of particular interest at the point  $n \in \mathbb{R}^3$  (on the contrary, we do so at  $0 \in \mathbb{R}^3$ ).

(iv) Prove that V is a  $C^{\infty}$  submanifold in  $\mathbb{R}^3$  of dimension 2 at every point belonging to  $V \setminus \{0\}$ .

**Background.** The fact of  $\phi$  not being an immersion at the points (0, t), therefore, is peculiar to  $\phi$ ; in this case, it does not imply singular behavior of  $\operatorname{im}(\phi)$  itself near n. Finally, without proof, we mention that V is not a submanifold in  $\mathbb{R}^3$  of dimension 2 at 0.

**Solution of Exercise 0.1.** (i)  $x \in V$  implies  $0 \le x_1^2 + x_2^2 = (1 - x_3)x_3^2$ , therefore  $0 \le 1 - x_3$ , that is,  $x_3 \le 1$ .

(ii) If 
$$x_3 = 1 - s^2$$
, then  $1 - x_3 = s^2$ . Accordingly, for  $x \in V$ ,

$$x_1^2 + x_2^2 = (1 - x_3)x_3^2 = (s(1 - s^2))^2$$
, so  $(x_1, x_2) = s(1 - s^2)(\cos t, \sin t)$ ,

for suitable  $t \in \mathbf{R}$ , on account of the parametrization of a circle by trigonometric functions. Thus we obtain  $V \subset \operatorname{im}(\phi)$ . Conversely, for every  $x \in \operatorname{im}(\phi)$ ,

$$x_1^2 + x_2^2 = (s(1-s^2))^2$$
 and  $(1-x_3)x_3^2 = s^2(1-s^2)^2$ , that is  $g(x) = 0$ .

(iii) Suppose, for  $h \in \mathbf{R}^2$ ,

$$D\phi(s,t)h = \begin{pmatrix} (1-3s^2)\cos t & -s(1-s^2)\sin t \\ (1-3s^2)\sin t & s(1-s^2)\cos t \\ -2s & 0 \end{pmatrix} \begin{pmatrix} h_1 \\ h_2 \end{pmatrix} = \begin{pmatrix} \star \\ \star \\ -2sh_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

If  $s \neq 0$ , it follows that  $h_1 = 0$ . The two top equations above then give

$$h_2 s(1-s^2) \sin t = h_2 s(1-s^2) \cos t = 0$$
, so  $s(1-s^2)h_2 = 0$ .

Accordingly, if  $s \notin \{-1, 0, 1\}$ , then  $h_2 = 0$  too; and therefore  $\phi$  is immersive in this case. On the other hand,

$$D\phi(\pm 1, t) = -2 \begin{pmatrix} \cos t & 0 \\ \sin t & 0 \\ \pm 1 & 0 \end{pmatrix}, \qquad D\phi(0, t) = \begin{pmatrix} \cos t & 0 \\ \sin t & 0 \\ 0 & 0 \end{pmatrix},$$

which shows that all three of these mappings in  $\text{Lin}(\mathbf{R}^2, \mathbf{R}^3)$  have a one-dimensional kernel. It is direct from the definition that  $\phi(\pm 1, t) = 0$  and  $\phi(0, t) = n$ , for all  $t \in \mathbf{R}$ .

(iv) We have, for  $x \in V$ ,

$$Dg(x) = (2x_1, 2x_2, -2x_3 + 3x_3^2) \in Lin(\mathbf{R}^3, \mathbf{R}).$$

This mapping fails to be surjective only if all its entries equal 0, which is the case only if x = 0 (the solution with  $x_3 = \frac{2}{3}$  does not belong to V). Hence, g is submersive at all points of  $V \setminus \{0\}$ ; and on the strength of the Submersion Theorem 4.5.2 we now obtain that V is a  $C^{\infty}$  manifold in  $\mathbb{R}^3$  of dimension 2 at all of its points, with the possible exception of the point 0.