Exercise 0.1 (Formulae of Serret–Frenet and tubular neighborhood of curve). Let $J \subset \mathbf{R}$ be an open interval in \mathbf{R} and let $\gamma : J \to \mathbf{R}^3$ be a C^{∞} curve in \mathbf{R}^3 . For any $s \in J$, denote by $\bot(s)$ the plane in \mathbf{R}^3 that contains the point $\gamma(s)$ and is perpendicular to the tangent vector $T(s) := \gamma'(s) \in \mathbf{R}^3$ of $\operatorname{im}(\gamma)$ at $\gamma(s)$. In this exercise, ' denotes the derivative of a mapping defined on J with respect to the variable in J.



- (i) Prove $\bot(s) = \{ x \in \mathbf{R}^3 \mid \langle x \gamma(s), T(s) \rangle = 0 \}.$
- (ii) Consider $x \in \mathbf{R}^3$ and suppose the function $s \mapsto ||x \gamma(s)||$ attains a minimum at $s_0 \in J$. Show $x \in \bot(s_0)$.

Now suppose that γ be parametrized by arc length, in other words, that ||T(s)|| = 1, and furthermore, that $\gamma''(s) \neq 0$, for all $s \in J$. Consider the mutually perpendicular unit vectors T(s), N(s) and $B(s) \in \mathbf{R}^3$ from Definition 5.8.1.

- (iii) Deduce that $N(s) \times B(s) = T(s)$ and $B(s) \times T(s) = N(s)$, for all $s \in J$.
- (iv) Show that $\bot(s) = \{ \gamma(s) + \lambda_1 N(s) + \lambda_2 B(s) \in \mathbf{R}^3 \mid \lambda \in \mathbf{R}^2 \}.$



Tubular surface.

Define tub(r), the *tubular surface* at a distance r > 0 from the curve γ , by means of

$$\operatorname{tub}(r) := \bigcup_{s \in J} \operatorname{tub}(s, r) := \bigcup_{s \in J} \{ x \in \bot(s) \mid ||x - \gamma(s)|| = r \}.$$

(v) Prove that $tub(r) = im(\phi)$ where

 $\phi:J\times\]-\pi,\ \pi\,]\to {\bf R}^3 \qquad {\rm is \ given \ by} \qquad \phi(s,\alpha)=\gamma(s)+r\cos\alpha\,N(s)+r\sin\alpha\,B(s).$

(vi) Using the formulae of Frenet-Serret from Section 5.8 show

$$\frac{\partial \phi}{\partial s}(s,\alpha) = (1 - r\kappa(s)\cos\alpha)T(s) - r\tau(s)\sin\alpha N(s) + r\tau(s)\cos\alpha B(s),$$

$$\frac{\partial \phi}{\partial \alpha}(s,\alpha) = -r\sin\alpha N(s) + r\cos\alpha B(s), \qquad \left\|\frac{\partial \phi}{\partial s} \times \frac{\partial \phi}{\partial \alpha}(s,\alpha)\right\| = r(1 - r\kappa(s)\cos\alpha).$$

- (vii) Verify that ϕ is an immersion under the assumption that $\kappa(s) < \frac{1}{r}$, for all $s \in J$. Deduce that for every point in $J \times [-\pi, \pi]$ there exists a neighborhood D such that $\phi(D) \subset \operatorname{tub}(r)$ is a C^{∞} submanifold in \mathbb{R}^3 of dimension 2.
- (viii) Suppose that γ is an embedding and that, for every $x \in tub(r)$, there exists a unique $s \in J$ such that $||x \gamma(s)|| \le r$. Use part (ii) to prove that ϕ is an embedding.

From now on assume that γ and ϕ are embeddings and that γ is of finite length.

(ix) Conclude area₂(tub(r)) = $2\pi r \operatorname{length}(\gamma)$.

Next, define Tub(r), the open *tubular neighborhood* of radius r of the curve γ , by means of

$$\operatorname{Tub}(r) := \bigcup_{0 \le \rho < r} \operatorname{tub}(\rho).$$

(x) Prove $\operatorname{vol}_3(\operatorname{Tub}(r)) = \pi r^2 \operatorname{length}(\gamma)$.

Furthermore, consider the C^{∞} mapping

$$\Psi: J \times \mathbf{R}^2 \to \mathbf{R}^3$$
 given by $\Psi(s,t) = \gamma(s) + t_1 N(s) + t_2 B(s).$

(xi) Compute

$$\det D\Psi(s,t) = \left\langle \frac{\partial\Psi}{\partial s}, \frac{\partial\Psi}{\partial t_1} \times \frac{\partial\Psi}{\partial t_2} \right\rangle(s,t) = 1 - \kappa(s) t_1.$$

Suppose $D(s) \subset \mathbf{R}^2$ is an open and Jordan measurable set and introduce the planar sets $U(s) \subset \bot(s)$, for $s \in J$, and the solid $U \subset \mathbf{R}^3$ by

$$U(s) = \{ \Psi(s,t) \in \mathbf{R}^3 \mid t \in D(s) \} \quad \text{and} \quad U = \bigcup_{s \in J} U(s).$$

(xii) Assume that $\Psi : \bigcup_{s \in J} \{s\} \times D(s) \to U$ is a C^{∞} diffeomorphism with positive Jacobi determinant and write $a(s) = \operatorname{area}_2(U(s))$. Prove

$$\operatorname{vol}_{3}(U) = \int_{J} \left(\operatorname{area} \left(D(s) \right) - \kappa(s) \int_{D(s)} t_{1} dt \right) ds$$
$$= \int_{\operatorname{im}(\gamma)} \left(a(s) - \kappa(s) \int_{U(s)} \langle y - \gamma(s), N(s) \rangle d_{2}y \right) d_{1}s.$$

(xiii) Apply the formula from the previous part in the case of the helix $\gamma : J =:]-\pi, \pi[\to \mathbb{R}^3$ as in Example 5.8.2 with $a = b = \frac{1}{2}\sqrt{2}$ and $D(s) =]0, 1[^2, \text{ for all } s \in J$, to show that $\operatorname{vol}_3(U) = 2\pi(1-\frac{\sqrt{2}}{4}) = 4.061743 \cdots$ in this case. **Background.** The result in part (x) above is a very special case of a result of H. Weyl: On the volume of tubes, Amer. J. Math. **61** (1939) 461-472. This paper has been very influential in modern differential geometry. Remarkable is that the formulae in parts (ix) and (x) are independent of the amount of "twisting" of the curve $im(\gamma)$.



Illustration for part (ix).

Solution of Exercise 0.1

- (i) Straightforward application of linear algebra.
- (ii) Consider $s \mapsto ||x \gamma(s)||^2 = \langle x \gamma(s), x \gamma(s) \rangle$. As it attains a minimum at s_0 , its derivative has to vanish at s_0 , in other words, on the basis of Corollary 2.4.3.(ii)

$$\langle x - \gamma(s_0), \gamma'(s_0) \rangle = \langle x - \gamma(s_0), T(s_0) \rangle = 0,$$
 that is $x \in \bot(s_0).$

- (iii) The matrix O(s) from Definition 5.8.1 maps the standard basis vectors e_1 , e_2 and e_3 in \mathbb{R}^3 to T(s), N(s) and B(s), respectively, and being an element of $\mathbf{SO}(3, \mathbb{R})$ preserves outer products. As $e_j \times e_{j+1} = e_{j+2}$ where the indices are taken modulo 3, the desired identities follow.
- (iv) N(s) and B(s) span the linear subspace of vectors in \mathbb{R}^3 perpendicular to T(s).
- (v) If $x = \phi(s, \alpha)$, then $x = \gamma(s) + \lambda_1 N(s) + \lambda_2 B(s) \in \bot(s)$ according to part (iv). Furthermore

$$||x - \gamma(s)|| = r||\cos \alpha N(s) + \sin \alpha B(s)|| = r$$

since N(s) and B(s) are mutually perpendicular unit vectors. Thus, im $\phi \subset \operatorname{tub}(r)$. Conversely, suppose $x \in \operatorname{tub}(r)$, then $x \in \operatorname{tub}(s, r)$, for some $s \in J$. Hence $x \in \bot(s)$ and $||x - \gamma(s)|| = r$, that is

$$x = \gamma(s) + r \cos \alpha N(s) + r \sin \alpha B(s) = \phi(s, \alpha),$$

for some $\alpha \in [-\pi, \pi]$. Therefore, $tub(r) \subset im \phi$.

(vi) Using part (iii) one finds

$$\begin{aligned} \frac{\partial \phi}{\partial s}(s,\alpha) &= \gamma'(s) + r \cos \alpha \, N'(s) + r \sin \alpha \, B'(s) \\ &= T(s) + r \cos \alpha \big(-\kappa(s) \, T(s) + \tau(s) \, B(s) \big) - r \sin \alpha \, \tau(s) \, N(s) \\ &= (1 - r\kappa(s) \cos \alpha) T(s) - r\tau(s) \sin \alpha \, N(s) + r\tau(s) \cos \alpha \, B(s), \\ \frac{\partial \phi}{\partial \alpha}(s,\alpha) &= -r \sin \alpha \, N(s) + r \cos \alpha \, B(s), \\ \frac{\partial \phi}{\partial s} \times \frac{\partial \phi}{\partial \alpha}(s,\alpha) &= -r \sin \alpha \big(1 - r\kappa(s) \cos \alpha \big) B(s) - r \cos \alpha \big(1 - r\kappa(s) \cos \alpha \big) N(s) \\ &\qquad -r^2 \tau(s) \sin \alpha \, \cos \alpha \, T(s) + r^2 \tau(s) \sin \alpha \, \cos \alpha \, T(s) \\ &= -r \big(1 - r\kappa(s) \cos \alpha \big) \big(\cos \alpha \, N(s) + \sin \alpha \, B(s) \big), \\ \Big\| \frac{\partial \phi}{\partial s} \times \frac{\partial \phi}{\partial \alpha}(s,\alpha) \Big\| &= r \big(1 - r\kappa(s) \cos \alpha \big). \end{aligned}$$

(vii) In view of the preceding part

$$r \kappa(s) < 1 \implies 1 - r\kappa(s) \cos \alpha > 0 \implies \frac{\partial \phi}{\partial s} \times \frac{\partial \phi}{\partial \alpha}(s, \alpha) \neq 0$$

which implies that $\frac{\partial \phi}{\partial s}(s, \alpha)$ and $\frac{\partial \phi}{\partial \alpha}(s, \alpha)$ are linearly independent, that is rank $D\phi(s, \alpha) = 2$, in other words, ϕ is an immersion. The second assertion is the Immersion Theorem 4.3.1.(i).

(viii) Consider $x \in tub(r)$. According to part (ii) we have $x \in \bot(s)$, for a unique $s \in J$. Hence $x \in tub(r, s)$, and by part (v) this implies $x = \phi(s, \alpha)$, for a unique $\alpha \in [-\pi, \pi]$; hence ϕ is injective. Next, suppose $x = \phi(s, \alpha)$. Then

$$\langle x - \gamma(s), N(s) \rangle = r \cos \alpha$$
 and $\langle x - \gamma(s), B(s) \rangle = r \sin \alpha$

yield that α depends continuously on x. As $\gamma(s) = x - r \cos \alpha N(s) - r \sin \alpha B(s)$, it follows that $\gamma(s)$ depends continuously on x; and so s itself too, because γ is an embedding. This proves that ϕ is an embedding.

(ix) As ϕ is an embedding one obtains from (v)

$$\operatorname{area}_{2}((\operatorname{tub}(r))) = \int_{J\times [-\pi,\pi]} \left\| \frac{\partial \phi}{\partial s} \times \frac{\partial \phi}{\partial \alpha}(s,\alpha) \right\| d(s,\alpha)$$
$$= \int_{J} \left(\int_{-\pi}^{\pi} r(1 - r\kappa(s)\cos\alpha) \, d\alpha \right) dr = 2\pi r \operatorname{length}(\gamma).$$

(x) Part (ix) implies directly

$$\operatorname{vol}_3(\operatorname{Tub}(r)) = \int_0^r \operatorname{area}_2(\operatorname{tub}(r)) dr = \pi r^2 \operatorname{length}(\gamma).$$

(xi) Since $\frac{\partial \Psi}{\partial t_1} \times \frac{\partial \Psi}{\partial t_2} = N \times B = T$, we only need to know the component of $\frac{\partial \Psi}{\partial s}$ along T for the computation of the inner product. Now we have, applying the formulae of Frenet–Serret once more,

$$\frac{\partial \Psi}{\partial s} = \gamma'(s) + t_1 N'(s) + t_2 B'(s) \equiv T - \kappa t_1 T = (1 - \kappa t_1) T.$$

(xii) The Change of Variables Theorem 6.6.1 implies

$$\operatorname{vol}_{3}(U) = \int_{U} dx = \int_{\bigcup_{s \in J} (\{s\} \times D(s))} (1 - \kappa(s) t_{1}) d(s, t)$$
$$= \int_{J} \left(\int_{D(s)} (1 - \kappa(s) t_{1}) dt ds = \int_{J} \left(\operatorname{area} (D(s)) - \kappa(s) \int_{D(s)} t_{1} dt \right) ds$$
$$= \int_{\operatorname{im}(\gamma)} \left(a(s) - \kappa(s) \int_{U(s)} \langle y - \gamma(s), N(s) \rangle d_{2}y \right) d_{1}s.$$

The last equality follows upon noting that $t \mapsto (\langle \Psi(t) - \gamma(s), N(s) \rangle, \langle \Psi(t) - \gamma(s), B(s) \rangle)$ is the identity mapping in \mathbb{R}^2 .

Introduce the *moments* $m_B(s)$ and $m_N(s)$ of the planar set U(s) about the lines $\gamma(s) + \mathbf{R} B(s)$ and $\gamma(s) + \mathbf{R} N(s) \subset \bot(s)$, respectively, by

$$m_B(s) = \int_{U(s)} \langle y - \gamma(s), N(s) \rangle d_2 y$$
 and $m_N(s) = \int_{U(s)} \langle y - \gamma(s), B(s) \rangle d_2 y.$

Then the *centroid* $c(s) \in \bot(s)$ of U(s) with respect to $\gamma(s)$ is defined by

$$c(s) = \frac{1}{a(s)}(m_B(s), m_N(s)).$$

These definitions then lead to the formulae

$$\operatorname{vol}_{3}(U) = \int_{\operatorname{im}(\gamma)} \left(a(s) - \kappa(s) \, m_{B}(s) \right) d_{1}s = \int_{\operatorname{im}(\gamma)} a(s) (1 - \kappa(s) \, c_{1}(s)) \, d_{1}s.$$

(xiii) Note that the helix is parametrized by arc length and that $\kappa(s) = \frac{1}{2}\sqrt{2}$ for all $s \in J$. Furthermore, Ψ is a diffeomorphism in this case, a(s) = 1 and $\int_{D(s)} t_1 dt = \int_0^1 t_1 dt_1 = \frac{1}{2}$. Thus, the assertion is a direct application of the formula in the preceding part.