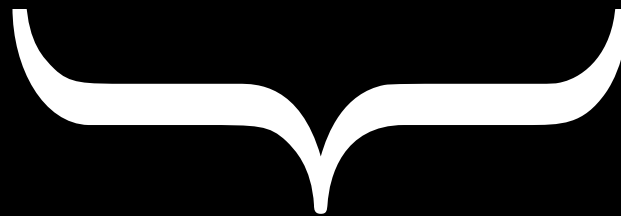
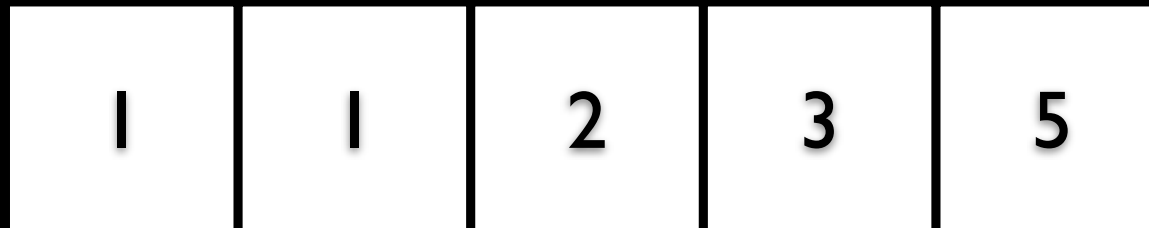


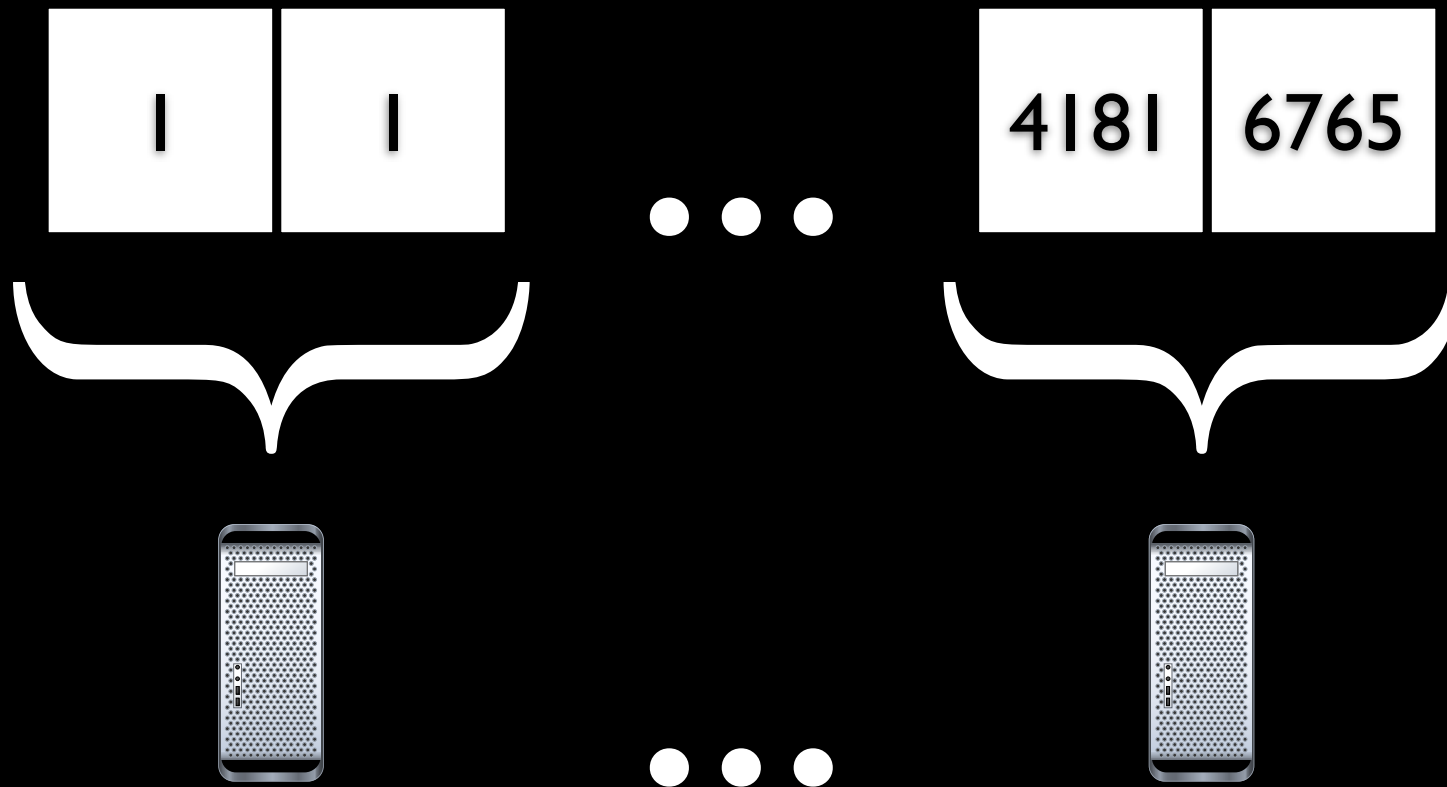
Dependent types for distributed arrays

Wouter Swierstra
joint work with Thorsten Altenkirch

Arrays



Distributed arrays



Golden Rule

Local access is quick;
remote access is slow.

Efficient code

- High-performance languages place restrictions on non-local array access.
- An operation that accidentally breaks the **Golden Rule** results in an exception.
- How can we avoid such exceptions?

Locality-aware IO

- Types with information about where the computation is executed.
- Think of $\text{IO } a \ p$ as the type of a computation at location p returning a value of type a .

Consequences

```
read :: Int -> Array -> IO Int ?
```

- The location depends on the array and the index you are accessing.

Consequences

```
read :: Int -> Array -> IO Int ?
```

- The **type** of this function depends on the **value** of its arguments.
- Grothoff, Palsberg, and Saraswat have designed a type system for distributed arrays, based on a dependently typed lambda calculus.

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash e : \text{int}} \quad (56)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash p : \text{pt } (p, R)} \quad (\text{where } p \in R) \quad (57)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash R : \text{reg } R} \quad (58)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash l : \Psi(l)} \quad (59)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash P : \text{pl } P} \quad (60)$$

$$\frac{\Psi; \varphi; \Gamma[x : t_1]; \text{unknown} \vdash e : t_2}{\Psi; \varphi; \Gamma; \text{here} \vdash \lambda x : t_1. e : t_1 \rightarrow t_2} \quad (61)$$

$$\frac{\Psi; \varphi \wedge \text{constraint}(k); \Gamma; \text{unknown} \vdash e : t}{\Psi; \varphi; \Gamma; \text{here} \vdash \text{lam } \alpha : k. e : \Pi \alpha : k. t} \quad (62)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash x : \Gamma(x)} \quad (63)$$

$$\frac{\Psi; \varphi; \Gamma; \text{here} \vdash e_1 : t_1 \rightarrow t_2 \quad \Psi; \varphi; \Gamma; \text{here} \vdash e_2 : t_1}{\Psi; \varphi; \Gamma; \text{here} \vdash e_1 e_2 : t_2} \quad (64)$$

$$\frac{\Psi; \varphi; \Gamma; \text{here} \vdash e_1 : \Pi \alpha : k. t_1 \quad \Psi; \varphi; \Gamma; \text{here} \vdash e_2 : t_2 \quad \vdash t_2 : k \triangleright W \quad \varphi \models (\text{constraint}(k))[\alpha := W]}{\Psi; \varphi; \Gamma; \text{here} \vdash e_1 \langle e_2 \rangle : t_1[\alpha := W]} \quad (65)$$

$$\frac{\Psi; \varphi; \Gamma[x : t_1]; \text{here} \vdash e : t_2 \quad \text{here} \neq \text{unknown}}{\Psi; \varphi; \Gamma; \text{here} \vdash \lambda^* x : t_1. e : t_1 \rightarrow t_2} \quad (66)$$

$$\frac{\Psi; \varphi \wedge \text{constraint}(k); \Gamma; \text{here} \vdash e : t \quad \text{here} \neq \text{unknown}}{\Psi; \varphi; \Gamma; \text{here} \vdash \text{lam}^* \alpha : k. e : \Pi \alpha : k. t} \quad (67)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash e : \text{reg } r} \quad (68)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash \text{new } t[e] : t[r]} \quad (68)$$

$$\frac{\Psi; \varphi; \Gamma; \text{here} \vdash y_1 : t[r_1] \quad \Psi; \varphi; \Gamma; \text{here} \vdash y_2 : \text{pt } (\sigma, r_2) \quad \varphi \models r_2 \subseteq_1 r_1 \quad \varphi \models \sigma \in_1 r_2 \quad \varphi \vdash \text{here} \equiv r_1[\Theta_1(\sigma, r_2)]}{\Psi; \varphi; \Gamma; \text{here} \vdash y_1[y_2] : t} \quad (69)$$

$$\frac{\Psi; \varphi; \Gamma; \text{here} \vdash y_1 : t[r_1] \quad \Psi; \varphi; \Gamma; \text{here} \vdash y_2 : \text{pt } (\sigma, r_2) \quad \varphi \models r_2 \subseteq_1 r_1 \quad \varphi \models \sigma \in_1 r_2 \quad \varphi \vdash \text{here} \equiv r_1[\Theta_1(\sigma, r_2)] \quad \Psi; \varphi; \Gamma; \text{here} \vdash e : t}{\Psi; \varphi; \Gamma; \text{here} \vdash y_1[y_2] = e : t} \quad (70)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash e : t[r]} \quad (71)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash e. \text{reg} : \text{reg } r} \quad (71)$$

$$\frac{\Psi; \varphi; \Gamma; \text{here} \vdash y_1 : t[r_1] \quad \Psi; \varphi; \Gamma; \text{here} \vdash y_2 : \text{pt } (\sigma, r_2) \quad \varphi \models r_2 \subseteq_1 r_1 \quad \varphi \models \sigma \in_1 r_2}{\Psi; \varphi; \Gamma; \text{here} \vdash y_1[\Theta_s y_2] : \text{pl } r_1[\Theta_s(\sigma, r_2)]} \quad (72)$$

$$\frac{\Psi; \varphi; \Gamma; \text{here} \vdash e_1 : \text{reg } r_1 \quad \Psi; \varphi; \Gamma; \text{here} \vdash e_2 : \text{reg } r_2}{\Psi; \varphi; \Gamma; \text{here} \vdash e_1 \cup_s e_2 : \text{reg } r_1 \cup_s r_2} \quad (73)$$

$$\frac{\Psi; \varphi; \Gamma; \text{here} \vdash e_1 : \text{reg } r_1 \quad \Psi; \varphi; \Gamma; \text{here} \vdash e_2 : \text{reg } r_2}{\Psi; \varphi; \Gamma; \text{here} \vdash e_1 \cap_s e_2 : \text{reg } r_1 \cap_s r_2} \quad (74)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash e : \text{reg } r} \quad (75)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash e +_s a : \text{reg } r +_s a} \quad (75)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash e : \text{pt } (\sigma, r)} \quad (76)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash e ++_s a : \text{pt } (\sigma ++_s r, r +_s a)} \quad (76)$$

$$\frac{\Psi; \varphi; \Gamma; \text{here} \vdash y_1 : \text{reg } r \quad \Psi; \varphi; \Gamma; \text{here} \vdash y_2 : \text{pl } \pi}{\Psi; \varphi; \Gamma; \text{here} \vdash y_1 \%_s y_2 : \text{reg } r \%_s \pi} \quad (77)$$

$$\frac{\Psi; \varphi; \Gamma; \text{here} \vdash e_1 : \text{reg } r \quad \Psi; \varphi \wedge (\alpha \in_1 r); \Gamma[x : \text{pt } (\alpha, r)]; \text{here} \vdash e_2 : \text{int} \quad \text{here} \neq \text{unknown}}{\Psi; \varphi; \Gamma; \text{here} \vdash \text{for } (x \text{ in } e_1) \{e_2\} : \text{int}} \quad (\text{where } \alpha \text{ is fresh}) \quad (78)$$

$$\frac{\Psi; \varphi; \Gamma[x : \text{pl } \alpha]; \text{here} \vdash e : \text{int} \quad \text{here} \neq \text{unknown}}{\Psi; \varphi; \Gamma; \text{here} \vdash \text{forallplaces } x(e) : \text{int}} \quad (\text{where } \alpha \text{ is fresh}) \quad (79)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash \text{forallplaces } x(e) : \text{int}} \quad (79)$$

$$\frac{\Psi; \varphi; \Gamma; \text{here} \vdash e_1 : t_1 \quad \Psi; \varphi; \Gamma; \text{here} \vdash e_2 : t_2}{\Psi; \varphi; \Gamma; \text{here} \vdash e_1; e_2 : t_2} \quad (80)$$

$$\frac{\Psi; \varphi; \Gamma; \text{here} \vdash y : \text{pl } \pi \quad \Psi; \varphi; \Gamma; \pi \vdash e : t}{\Psi; \varphi; \Gamma; \text{here} \vdash \text{at } (y) \{e\} : t} \quad (81)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash e : t \quad \varphi \vdash t \equiv t'} \quad (82)$$

$$\frac{}{\Psi; \varphi; \Gamma; \text{here} \vdash e : t'} \quad (82)$$

A. Proof of Type Preservation

Here is the statement of Type Preservation (Theorem 1):

For a place P , let $Q \in \{P, \text{unknown}\}$. If $\Psi; \varphi; \Gamma; Q \vdash e : t, \models H : \Psi$, and $P \vdash (H, e) \rightsquigarrow (H', e')$, then we have Ψ', t' such that $\Psi \triangleleft \Psi'$, $\Psi'; \varphi; \Gamma; Q \vdash e' : t', \models H' : \Psi'$, and $\varphi \vdash t \equiv t'$.

Proof. We proceed by induction on the structure of the derivation of $\Psi; \varphi; \Gamma; Q \vdash e : t$. There are now twenty-five subcases depending on which one of the type rules was the last one used in the derivation of $\Psi; \varphi; \Gamma; Q \vdash e : t$.

Domain-specific embedded type systems

- Designing a type system is a lot of work!
- Can't we use enforce these invariants using a general purpose dependently typed host language, such as Agda?
- Implementation and meta-theory for free!

Overview

- Embed the syntax and semantics of distributed array operations in a dependently typed language host language;
- statically enforce locality constraints;
- extract efficient code from our specification.

Terminology

- Any processor that executes code and stores data is referred to as a **place**.
- We will call an index in the array a `Point`
- We postulate a global **distribution**:

`distr : Array -> Point -> Place`

Syntax - I

```
data IO (a : Set) : Place -> Set
```

```
Return : a -> IO p a
```

```
Read : (a : Array)
```

```
  -> (i : Point)
```

```
  -> (Int -> IO (distr a i) a)
```

```
  -> IO (distr a i) a
```

Syntax - II

```
data IO (a : Set) : Place -> Set
```

```
...
```

```
Write : (a : Array)
```

```
  -> (i : Point) -> Int
```

```
  -> IO (distr a i) a
```

```
  -> IO (distr a i) a
```

Syntax - III

```
data IO (a : Set) : Place -> Set
```

```
...
```

```
At : (q : Place)
```

```
  -> IO q ()
```

```
  -> IO p a
```

```
  -> IO p a
```


Auxiliary definitions

- We can define smart constructors:

```
read : (a : Array)
```

```
  -> (i : Point)
```

```
  -> IO (distr a i) Int
```

- and show that the IO data type is a monad.

Example: for

```
for : (Point -> IO p ())  
    -> Array -> IO p ()
```

```
for io a = worker 0
```

```
  where worker i =
```

```
    if i == (size a) - 1 then
```

```
      then return ()
```

```
      else io i >> worker (i+1)
```

Example: dmap

```
dmap : (Int -> Int)
      -> Array -> IO p ()

dmap f a =
  for (\i -> at (distr a i)
      (read a i >> \x ->
        write a i (f x)))
```

Heap

```
data Heap = List (List Int)  
type Array = Int  
type Point = Int
```

Semantics - I

```
run : (p : Place) -> IO a p  
      -> Heap -> (a, Heap)
```

```
run p (Return x) h = (x, h)
```

```
run p (At q io1 io2) h =  
      run p io2 (snd (run io1 h))
```

Semantics - II

```
run : (p : Place) -> IO a p  
      -> Heap -> (a, Heap)
```

```
run ? (Write a i x wr) h =  
      run ? wr (updateHeap a i x h)
```

```
run ? (Read a i rd) h =  
      run ? (rd (h !! a !! i))
```

Semantics - II

```
run : (p : Place) -> IO a p
      -> Heap -> (a, Heap)
run ? (Write a i x wr) h =
      run ? wr (updateHeap a i x h)
```

How do can we be sure we are
not breaking the **Golden Rule**?

Why is this Haskell program well-typed?

```
data EQ a b where
```

```
  Refl :: EQ a a
```

```
coerce :: EQ a b -> a -> b
```

```
coerce Refl x = x
```


Learning from pattern matching

```
run .(distr a i)
    (Write a i x wr) h
= run (distr a i)
      wr (updateHeap a i x h)
```

Limitations

- This semantics is partial – that is, the lookup functions may fail...
- No allocation of new arrays
- Both of these points are solved in the paper.

Even more limitations

- No multi-dimensional arrays;
- Arrays may only store integers;
- A fixed, global distribution;
- Synchronous semantics;
- And we need a lot of these things to do interesting examples!

Conclusions

- Plenty of limitations – but the approach seems viable.
- *Domain-specific embedded type systems are the way to go!*