

1

# The functional essence of imperative binary search trees

Anton Lorenzen, Daan Leijen, Sam Lindley and Wouter Swierstra

Edinburgh, MSR and Utrecht

```
data List a = Nil | Cons a (List a)
```

```
reverse :: List a → List a
```

```
reverse xs = reverseAcc xs Nil
```

#### where

```
reverseAcc :: List a → List a → List a
reverseAcc Nil acc = acc
reverseAcc (Cons x xs) acc = reverseAcc xs (Cons x acc)
```

*Compositional* programs - each assembled from other functions that can be tested and verified independently.

There are a variety of *elementary* techniques for verifying that a program is correct:

- testing automatically;
- writing pen and paper proofs;
- developing a formal proofs using proof assistants.

*Compositional* programs - each assembled from other functions that can be tested and verified independently.

There are a variety of *elementary* techniques for verifying that a program is correct:

- testing automatically;
- writing pen and paper proofs;
- developing a formal proofs using proof assistants.

How does this compare to list reversal in an imperative language?

### Linked list reversal in C

```
list_t* reverse( list_t* curr ) {
  list_t* prev = NULL;
  while(curr ≠ NULL) {
    list_t* next = curr→tail;
    curr→tail = prev;
    prev = curr;
    curr = next; }
  return prev; }
```

Each cell in the list stores a value and a pointer to the remaining lists.

To reverse the list, we update the pointer in each cell to point to the *previous* element, until there are no cells left.



# **In-place execution**



# **In-place execution**



# **In-place execution**



Giving a *formal proof* that such a program is correct is **very hard**.

- Hoare logic is not suitable for reasoning about this kind of imperative code: what if the list structure in memory has cycles? Or if the two pointers map to lists sharing the same memory locations?
- Extensions of Hoare logic, notably separation logic, have had a lot of success but these methods are certainly not elementary.

Giving a *formal proof* that such a program is correct is **very hard**.

- Hoare logic is not suitable for reasoning about this kind of imperative code: what if the list structure in memory has cycles? Or if the two pointers map to lists sharing the same memory locations?
- Extensions of Hoare logic, notably separation logic, have had a lot of success but these methods are certainly not elementary.

But the C algorithm has an important property: it is executed *in-place* - it does not need to allocate new memory or deallocate unused memory.

#### **Functional reverse**



### **Towards in-place functional programming**



```
reverseAcc :: List a \rightarrow List a \rightarrow List a
reverseAcc Nil acc = acc
reverseAcc (Cons x xs) acc = reverseAcc xs (Cons x acc)
```

The reverseAcc function has a few important properties:

- we can see that we are matching on one Cons cell on the left;
- and allocating one new Cons cell on the right.
- all other variables (like x or acc) are used linearly, i.e. they are not copied or discarded.

We will call such programs *fully in-place* – or fip for short.

### Making this more precise..

$ \begin{array}{ll} \Gamma & ::= & \varnothing \   \ \Gamma, x \   \ \Gamma, \diamond_k & (\text{owned environment}) \\ \Delta & ::= & \varnothing \   \ \Delta, y & (\text{borrowed environment}) \end{array} $	
$\Delta \mid x \vdash x$ VAR	$\Delta \mid \varnothing \vdash C$ atom
$\frac{\Delta \mid \Gamma_i \vdash \nu_i}{\Delta \mid \Gamma_1, \dots, \Gamma_n \vdash (\nu_1, \dots, \nu_n)} \text{ tuple}$	$\frac{\Delta \mid \Gamma_i \vdash \nu_i}{\Delta \mid \Gamma_1, \dots, \Gamma_k, \diamond_k \vdash C^k \nu_1 \dots \nu_k} \text{ reuse}$
$\overline{y} \in \Delta, \operatorname{dom}(\Sigma)  \Delta \mid \Gamma \vdash e$ $\Delta \mid \Gamma \vdash f(\overline{y}; e)  \text{Call}$	$\frac{\left. \begin{array}{c c} \Delta,\Gamma_2 \mid \Gamma_1 \vdash e_1 & \Delta \mid \Gamma_2,\Gamma_3,\overline{x} \vdash e_2 & \overline{x} \notin \Delta,\Gamma_2,\Gamma_3 \end{array} \right.}{\left. \Delta \mid \Gamma_1,\Gamma_2,\Gamma_3 \vdash \text{let } \overline{x} = e_1 \text{ in } e_2 \end{array}} \text{ Let }$
$\frac{y \in \Delta  \Delta \mid \Gamma \vdash e}{\Delta \mid \Gamma \vdash y \; e} \text{ bapp}$	$ \begin{array}{c c} y \in \Delta & \Delta, \overline{x}_i \mid \Gamma \vdash e_i & \overline{x}_i \notin \Delta, \Gamma \\ \hline \Delta \mid \Gamma \vdash \text{ match } y \mid C_i \ \overline{x}_i \ \mapsto e_i \mid \end{array} \text{ BMATCH} \end{array} $
$\frac{\Delta \mid \Gamma \vdash e}{\Delta \mid \Gamma, \diamond_0 \vdash e} \text{ Empty}$	$\frac{\Delta \mid \Gamma, \overline{x}_{i}, \diamond_{k} \vdash e_{i}  k =  \overline{x}_{i}   \overline{x}_{i} \notin \Delta, \Gamma}{\Delta \mid \Gamma, x \vdash \text{match}! x \{ C_{i} \overline{x}_{i} \mapsto e_{i} \}} \text{ dmatch!}$
⊢ Ø Defbase	$\frac{ \vdash \Sigma'  \overline{y} \mid \overline{x} \vdash e}{ \vdash \Sigma', f(\overline{y}; \overline{x}) = e} \text{ deffun}$
Fig. 4. Well-formed FIP expressions, where the multiplicity of each variable in $\Gamma$ is 1.	

These rules (and corresponding memory reuse) have been implemented in the Koka compiler.

Re-implementing the reverse function in Koka becomes:

```
fip fun reverse-acc( xs : list<a>, acc : list<a> ) : list<a>
  match xs
  Cons(x,xx) → reverse-acc( xx, Cons(x,acc) )
  Nil → acc
```

The **fip** keyword indicates that a function can be executed *fully in place*.

The compiler checks that each function with the fip annotation can be executed without (de)allocating memory.

### **Beyond list reversal**

List reversal is not so interesting - what about algorithms for trees?

type tree Node( left : tree, key : int, right : tree ) Leaf

Let's look at algorithms on *binary search trees*.

In particular, *restructuring* binary search trees, where accessing an element restructures the tree.

List reversal is not so interesting - what about algorithms for trees?

type tree Node( left : tree, key : int, right : tree ) Leaf

Let's look at algorithms on *binary search trees*.

In particular, restructuring binary search trees, where accessing an element restructures the tree.

We aim to define an access function:

```
fun access-spec (t : tree, k : key) : tree
Node (smaller(t,k), k, bigger(t,k))
```

which inserts the key, if it is not yet present, and moves it to the root if it is.

### Rotation (Allen & Munro, 1976)



fip fun rotateRight (t : tree) : tree

match t

(Node (Node (t2, a, t3), f, t1)  $\rightarrow$  Node (t2, a, Node (t3, f, t1))

Allen & Munroe suggest *repeated* rotations, ensuring the key being looked up is moved to the root of the new binary tree.

In this fashion, frequently accessed elements naturally 'bubble up' to the root of the tree.

Can we give a purely functional—yet in place—algorithm?

```
fun lookup (k : int, t : tree)
match t with
Node (l, x, r) → if k = x
then x
else if k < x
then lookup (k, l)
else lookup (k, r)</pre>
```

This is not in place: we only ever recurse on one subtree.

```
fun lookup (k : int, t : tree)
match t with
Node (l, x, r) → if k == x
then x
else if k < x
then lookup (k, l)
else lookup (k, r)</pre>
```

This is not in place: we only ever recurse on one subtree.

#### Key idea

Search through the tree recursively, accumulating the unvisited subtrees on a 'stack'.

Once we find the element, unwind the 'stack' to rebuild the new tree, rotating as we move back up.

# **Stacks**

A simple stack of subtrees will not work – to reconstruct a binary search tree we need to record if we went left or right!

```
type zipper
```

Done

```
// we went left; the tree stores bigger elements than the key being accessed
Left(up : zipper, x : int, right : tree )
// we went right; the tree stores smaller elements than the key being accessed
Right(left : tree, x : int, up : zipper )
```

### **Stacks**

A simple stack of subtrees will not work – to reconstruct a binary search tree we need to record if we went left or right!

```
type zipper
```

Done

```
// we went left; the tree stores bigger elements than the key being accessed
Left(up : zipper, x : int, right : tree )
// we went right; the tree stores smaller elements than the key being accessed
Right(left : tree, x : int, up : zipper )
```

Using these zippers we can construct a pair of functions:

```
// search through the tree for the given key
fun access (key : int, t : tree, z : zipper) : (tree, zipper)
// rebuild the entire tree, rotating as necessary
fun rebuild (t : tree, z : zipper) : tree
```

```
fip(1) fun access(t : tree, k : int, z : zipper)
match t
Node(l,x,r) → if x == k then rebuild(z, Node(l,k,r))
else if k < x then access(l, k, Left(z,x,r))
else access(r, k, Right(l,x,z))
Leaf → rebuild(z, Node(Leaf,k,Leaf) )</pre>
```

The access function has the same structure as the (more familiar) lookup function.

If the key is already present, the tree is restructured; otherwise the new key is inserted.

The function is in-place, but may do at most one allocation.

```
fip fun access (...)
Node(1,x,r) → if ... then access(1, k, Left(z,x,r))
```

Why is this in-place? We match on a node, but extend our zipper?

```
fip fun access (...)
Node(1,x,r) → if ... then access(1, k, Left(z,x,r))
```

Why is this in-place? We match on a node, but extend our zipper?

Memory re-use is not restricted to the same constructors or even the same types!

Instead, we only check that the variables are not duplicated or discarded;

And that the *sizes* of deallocations and allocations line up.

```
fip fun rebuild(z : zipper, t : tree )
match z
Done → t
Right(1,x,z) → match t // we went right looking for k
Node(s,k,b) → rebuild(z, Node( Node(1,x,s), k, b))
Left(z,x,r) → match t // we went left looking for k
Node(s,k,b) → rebuild(z, Node( s, k, Node(b,x,r)))
```

Now we rebuild the entire tree, popping elements off the zipper.

In each case, we rotate the tree as required to ensure the result remains a binary search tree.

From this definition, it is easy to see that the key k stays at the root – just as we wanted!

### **Zippers - defunctionalised continuations**

How do you come up with code like this?

How do you come up with code like this?

It is 'just' the tail recursive version arising from the defunctionalised CPS-transformed direct implementation that is in-place, but not tail recursive:

```
fun access( t : tree, k : key )
match t
Node(1,x,r) → if x < k then match access(r,k) // lookup and rotate
Node(s,y,b) → Node( Node(1,x,s), y, b)
elif x > k then match access(1,k) // lookup and rotate
Node(s,y,b) → Node( s, y, Node(b,x,r))
else Node(1,k,r)
Leaf → Node(Leaf,k,Leaf)
```

And the implementation above follows calculationally from the original access-spec.

The zippers are used as a 'stack of trees' – we have immediate access to the tree we last added to the zipper.

But that's not always what we want: many *top down* algorithms work by *accumulating* (unfinished) trees, extending the tree with new nodes at the fringe.

The zippers are used as a 'stack of trees' – we have immediate access to the tree we last added to the zipper.

But that's not always what we want: many *top down* algorithms work by *accumulating* (unfinished) trees, extending the tree with new nodes at the fringe.

Consider the following fragment of code from the previous slide:

```
Node(1,x,r) →

if x < k then match access(r,k) // lookup and rotate

Node(s,y,b) → Node( Node(1,x,s), y, b)
```

• • •

We *could* implement these unfinished trees as zippers, just as we *could* implement queues using lists...

Koka let's you write *constructor contexts*, or elements of an algebraic datatypes with a single hole:

Node(Leaf, 3 , □)

Koka let's you write constructor contexts, or elements of an algebraic datatypes with a single hole:

Node(Leaf, 3 , □)

There are two operations on these contexts:

fun (++) : ctx → ctx → ctx // append contexts
fun (++.) : ctx → tree → tree // fill in the hole

Using such contexts, we can write a tail recursive map function in a single pass:

```
fip fun map-td(xs : list<a>, f : a → b, acc : list-ctx<b> ) : list<b>
match xs
Cons(x,xs) → map-td( xx, f, acc ++ Cons(f(x), □) )
Nil → acc ++. Nil
```

And start our map with an empty accumulator:

```
fip fun map(xs,f)
map-td(xs, f, □)
```

This pattern – accumulating (partial) results in a constructor context – pops up again and again.

We could implement constructor contexts using functions – similar to 'difference lists' – or zippers.

We could implement constructor contexts using functions – similar to 'difference lists' – or zippers.

But instead, we represent them as 'Minamide tuples', allocating an additional pointer to the context's hole.



Then *all* operations on constructor contexts require constant time.

. . .

Let's take a closer look at the direct implementation:

```
Node(1,x,r) →
if x < k then match access(r,k) // lookup and rotate
Node(s,y,b) → Node( Node(1,x,s), y, b)</pre>
```

We can also phrase this in terms of two accumulating constructor contexts – the left and right subtrees – where we collect the parts of the trees we do not visit.

```
fip(1) fun access-td(t : tree, k : key, accl : ctx, accr : ctx) : tree
match t
Node(1,x,r) →
if x < k then access-td( r, k, accl ++ Node(1,x,□), accr )
elif x > k then access-td( 1, k, accl, accr ++ Node(□,x,r) )
else Node( accl ++. 1, x, accr ++. r )
Leaf → Node( accl ++. Leaf, k, accr ++. Leaf)
```

# What about the imperative implementations?

#### What about the imperative implementations?

```
Definition heap_mtr_insert_td : val :=
 fun: ( name, root ) {
   var: left dummy := #0 in
   var: right dummy := #0 in
   var: node := root in
   var: left hook := &left dummy in
   var: right hook := &right dummy in
   while: ( true ) {
     if: ( node != #0) {
       if: ( node->value == name ) (
         *left hook = node->left::
         *right hook = node->right::
         root = node::
         break
       else (
         if: ( node->value > name )
           sright hook = node::
           right_hook = &(node->left);;
           node = node->left
         else
           *left hook = node::
           left_hook = &(node->right);;
           node = node->right
      else
       *left book = #0::
       *right hook = #0::
       root = AllocN #3 #0::
       root->value = name::
       break
   }::
                                                        bottom:
   root->left = left_dummy;;
   root->right = right_dummy;;
   ret: root
```

node := root: left\_hook := addr(left(dummy)); right\_hook := addr(right(dummy)); while node # null do if value(node) = name then begin O(left hook) := left(node): 0(right\_hook) := right(node); root := node: go to bottom end: if value(node) > name then begin O(right hook) := node: right\_hook := addr(left(node)); node := left(node)end else begin O(left hook) := node: left\_hook := addr(right(node)); node := right(node)end: 0(left hook) := null:O(right hook) := null: root := new\_node ( ); value(root) := name; left(root) := left(dummy): right(root) := right(dummy)

Fig. 1. The move-to-root top-down algorithm formalized in AddressC on the left, versus a screenshot of Stephenson's published algorithm on the right

Using a proof assistant, we have given a formal proof of correctness of both top-down and bottom-up move to root trees.

That is, we can prove a Hoare triple of (roughly) the following form:

```
Lemma heap_mtr_insert_td_correct (k : key) (p : ptr) (t : tree) :
    { is_tree t p }
    heap_mtr_insert_td k p
    { is_tree (mtr_insert_td k t) p }.
```

In this way, we prove that the functional version (mtr\_insert\_td) coincides precisely with the (published) imperative algorithms (heap\_mtr\_insert\_td).

• These proofs are non-trivial! If you've ever tried to write out a formal proof in Hoare logic for any program longer than 5 lines, you know there is a lot of bookkeeping involved.

- These proofs are non-trivial! If you've ever tried to write out a formal proof in Hoare logic for any program longer than 5 lines, you know there is a lot of bookkeeping involved.
- Theorem proving technology (Coq and Iris) are fairly impressive the proof is about 50 loc, half of which is formulating the loop invariant.

- These proofs are non-trivial! If you've ever tried to write out a formal proof in Hoare logic for any program longer than 5 lines, you know there is a lot of bookkeeping involved.
- Theorem proving technology (Coq and Iris) are fairly impressive the proof is about 50 loc, half of which is formulating the loop invariant.
- The functional implementation captures the key parts of the specification it is essential for spelling out the loop invariant.

- These proofs are non-trivial! If you've ever tried to write out a formal proof in Hoare logic for any program longer than 5 lines, you know there is a lot of bookkeeping involved.
- Theorem proving technology (Coq and Iris) are fairly impressive the proof is about 50 loc, half of which is formulating the loop invariant.
- The functional implementation captures the key parts of the specification it is essential for spelling out the loop invariant.
- This is (to the best of our knowledge) the first formal proof of these algorithms.

Move-to-root trees guarantee that a freshly accessed key always moves to the root.

But it does not do any *rebalancing* along the way...

Move-to-root trees guarantee that a freshly accessed key always moves to the root.

But it does not do any *rebalancing* along the way...

The more established splay trees (Sleator and Tarjan 1985) address precisely this issue.

The key difference is in the rebuild function that tries to rebalance the resulting tree.

Similarly, the more recent *zip trees* (Tarjan et al. 2021) can be shown to have a fully in-place functional counterpart.

Comparing the same algorithm across different languages is always going to be unfair.

- Koka, Haskell, and OCaml have automatic memory management as opposed to C;
- Haskell and OCaml use mark-and-sweep garbage collectors; Koka uses reference counting.
- Koka uses arbitrary precision integers for keys and all comparisons and arithmetic operations include branches for the case where big integer arithmetic is required;
- Haskell is lazy, most other functional languages are not.

#### **Benchmarks**



10M pseudorandom insertions of a key between 0 and 100.000 on an initially empty tree.

We start with a simple functional specification, access-spec.

We start with a simple functional specification, access-spec.

We write a 'direct style' recursive implementation.

We start with a simple functional specification, access-spec.

We write a 'direct style' recursive implementation.

Transforming this to fip functions is *guaranteed* to produce fast code.



*Is there a way to combine the indulgences of impurity with the benefits of purity?* — Phil Wadler [1990]

• Best-of-both worlds approach: purely functional programs with low memory usage.

- Best-of-both worlds approach: purely functional programs with low memory usage.
- Okasaki's famous book on Purely functional datastructures is chock-full of fip algorithms...

- Best-of-both worlds approach: purely functional programs with low memory usage.
- Okasaki's famous book on Purely functional datastructures is chock-full of fip algorithms...
- Just as finding a *tail recursive* function yields a program that can be executed in constant *stack space*, finding a *fip* function yields a program that can be executed in constant *heap space*.

- Best-of-both worlds approach: purely functional programs with low memory usage.
- · Okasaki's famous book on Purely functional datastructures is chock-full of fip algorithms...
- Just as finding a *tail recursive* function yields a program that can be executed in constant *stack space*, finding a *fip* function yields a program that can be executed in constant *heap space*.
- Elementary verification techniques only! Structural induction on trees suffices.

- Best-of-both worlds approach: purely functional programs with low memory usage.
- · Okasaki's famous book on Purely functional datastructures is chock-full of fip algorithms...
- Just as finding a *tail recursive* function yields a program that can be executed in constant *stack space*, finding a *fip* function yields a program that can be executed in constant *heap space*.
- Elementary verification techniques only! Structural induction on trees suffices.
- Modern proof assistants can relate the functional and imperative versions the functional algorithm captures the essence of the loop invariant.

- Best-of-both worlds approach: purely functional programs with low memory usage.
- · Okasaki's famous book on Purely functional datastructures is chock-full of fip algorithms...
- Just as finding a *tail recursive* function yields a program that can be executed in constant *stack space*, finding a *fip* function yields a program that can be executed in constant *heap space*.
- Elementary verification techniques only! Structural induction on trees suffices.
- Modern proof assistants can relate the functional and imperative versions the functional algorithm captures the essence of the loop invariant.
- But if you need to write the functional version to verify imperative code why write imperative programs to begin with?

**Questions?** 

Even if a function is fip, it is not *always* safe to execute it in place.

Consider the following example:

```
fun makePalindrome( xs : list<a>) : list<a>
  return (append(xs, reverse(xs))
```

Clearly this call to reverse should not run in place!

Even if a function is fip, it is not *always* safe to execute it in place.

Consider the following example:

```
fun makePalindrome( xs : list<a>) : list<a>
  return (append(xs, reverse(xs))
```

Clearly this call to reverse should not run in place!

When can we tell it is safe to execute fip functions in place?

Koka uses a reference counted garbage collection.

As a result, we know at execution time how many references exist to any given value.

We can check if a reference is unique at run-time and re-use existing memory locations when possible:

```
fip fun reverse-acc( xs : list<a>, acc : list<a> ) : list<a>
match xs
Cons(x,xx) ->
val addr = if is-unique(xs) then &xs else { dup(x); dup(xx); decref(xs); alloc(2) }
reverse-acc( xx, Cons@addr(x,acc) )...
```

# Zippers

The original zipper paper describes a functional approach to navigating through a tree (Huet 1997).

A pair of a zipper and tree, allows you to 'move focus' to a child, without loss of information:

```
fip fun left (t : tree, z : zipper) : (tree, zipper)
match t
Node (1, x, r) → (1, Left(z,x,r))
```

# Zippers

The original zipper paper describes a functional approach to navigating through a tree (Huet 1997).

A pair of a zipper and tree, allows you to 'move focus' to a child, without loss of information:

```
fip fun left (t : tree, z : zipper) : (tree, zipper)
match t
Node (1, x, r) → (1, Left(z,x,r))
```

Huet (1997) writes:

*Efficient destructive algorithms on binary trees may be programmed with these completely applicative primitives, which all use constant time, since they all reduce to local pointer manipulation.* 

Using our fip calculus we can make this precise – and check this property statically!

Zipper-based traversal turn out to be very useful.

```
fip fun load (t : tree, f : int → int, z : zipper) : tree
  match t
    Node (1. x. r) \rightarrow load(l.f.Left(z. f(x), r))
    Leaf \rightarrow unload(z,f,Leaf)
fip fun unload (z : zipper, f : int → int, t : tree) : tree
  match z
    Left (z.x.r) \rightarrow load(r,f,Right(t,x,z))
    Right (1,x,z) \rightarrow unload(z,f,Node(1,x,t))
    Done
                    -> t
```

This traversal does not allocate any heap or stack space – yet works for any\* data type!

# **Rebuilding splay trees**

#### Self-Adjusting Binary Search Trees

DANIEL DOMINIC SLEATOR AND ROBERT ENDRE TARJAN

AT&T Bell Laboratories, Murray Hill, NJ







```
fip fun rebuild(z : zipper, t : tree ) : tree
  match tree
     Node(tl,tx,tr) → match z
       Done \rightarrow Node(tl.tx.tr)
       Right(rl.rx.Done) -> Node(Node(rl.rx.tl).tx.tr)
                                                                                        // zia
       Left(Done.lx.lr) → Node(tl.tx.Node(tr.lx.lr))
       Right(rl,rx,Right(l,x,up)) -> rebuild(up, Node(Node(Node(l,x,rl),rx,tl),tx,tr)) // ziazia
       Left(Right(1,x,up),lx,lr) -> rebuild(up, Node(Node(1,x,t1),tx,Node(tr,lx,lr)))
       Right(rl,rx,Left(up,x,r)) → rebuild(up, Node(Node(rl,rx,tl),tx,Node(tr,x,r))) // zigzag
       Left(Left(up,x,r),lx,lr) → rebuild(up, Node(tl,tx,Node(tr,lx,Node(lr,x,r))))
```

### So what's our the papers

- In place versions of:
  - Splay trees;
  - Schorr Waite traversal of trees;
  - · Generic map over any algebraic datatype;
  - Red black tree insertion;
  - Mergesort;
  - Finger tree insertions;
  - ...
- Top-down & bottom-up implementations of:
  - move to root trees;
  - splay trees;
  - zip trees;
  - proofs that they 'are all equal';
  - proofs that the functional versions coincide with published imperative ones.
- Lots of metatheory, showing that it is *safe* to execute fip programs in place.