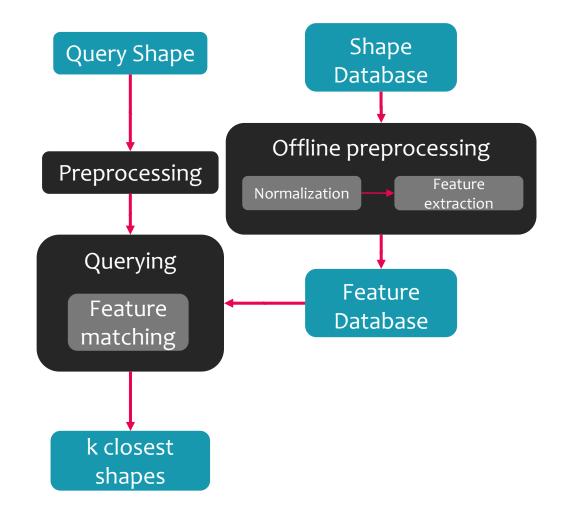
3D Shape Retrieval

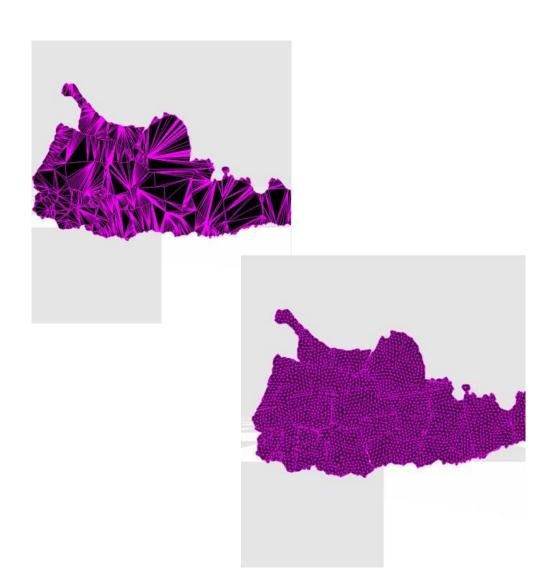
Multimedia Retrieval 2020

Resul Çelik, Julian Thijssen



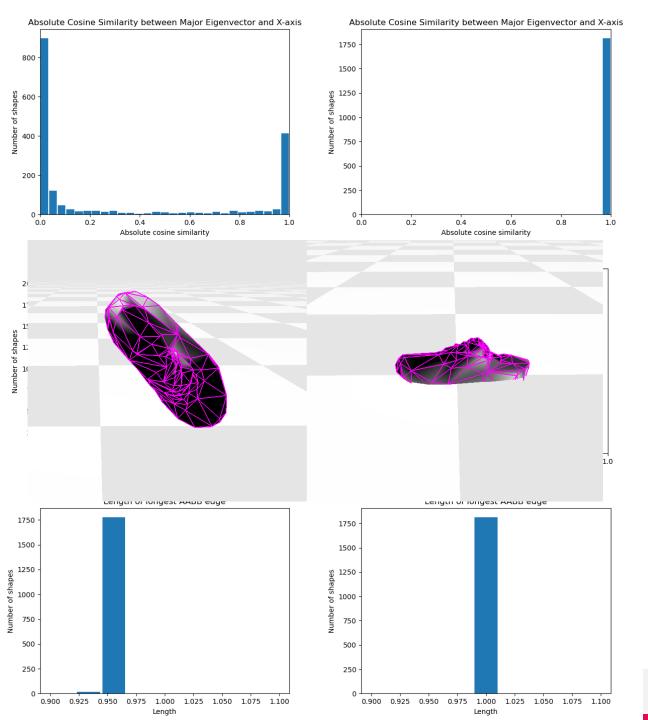
Top-Level Overview

Processing and cleaning



Processing and cleaning

1. Remeshing

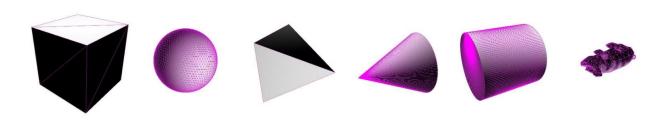


Processing and cleaning

- 2. Orientational normalization
- 3. Positional normalization
- 4. Scale normalization

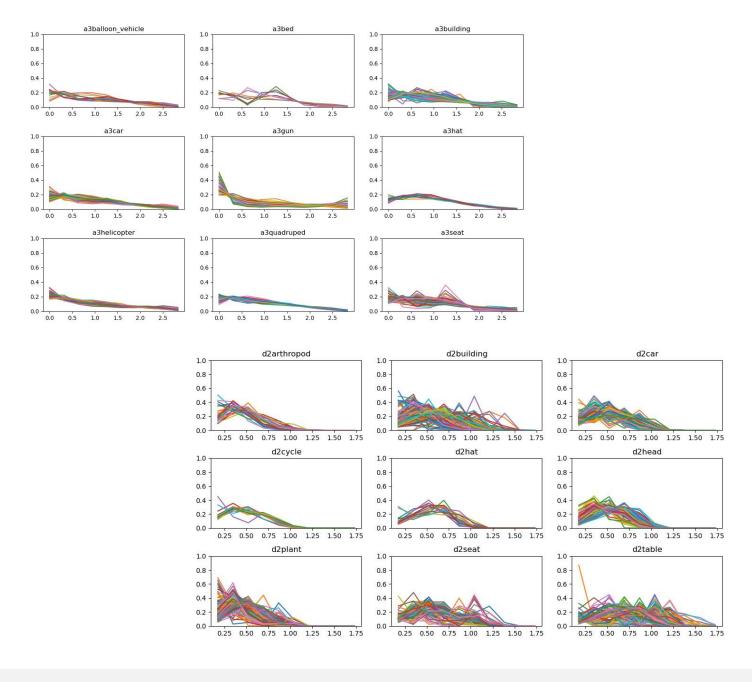
Feature extraction

Primitive feature values						
Feature	Cube	Sphere	Pyramid	Cone	Cylinder	Pig (m100)
Surface Area	6	3.142	3.236	2.541	4.712	1.15
Volume	1	0.524	0.333	0.262	0.785	0.07
Compactness	0.806	1	0.718	0.794	0.874	0.68



Feature extraction

- Elementary Shape Descriptors
- Primitive shapes

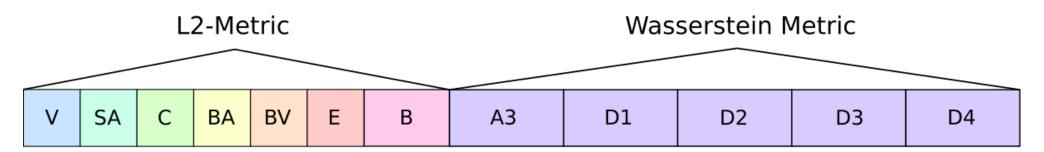


Feature extraction

- Shape Property Descriptors
- Histograms

Querying

Feature Vector



Single features

V = Volume

SA = Surface Area

C = Compactness

BA = AABB Area

BV = AABB Volume

E = Eccentricity

B = AABB Dimensions

Histogram features

A3 = Angle between 3 random vertices

D1 = Distance to random vertex

D2 = Distance between 2 random vertices

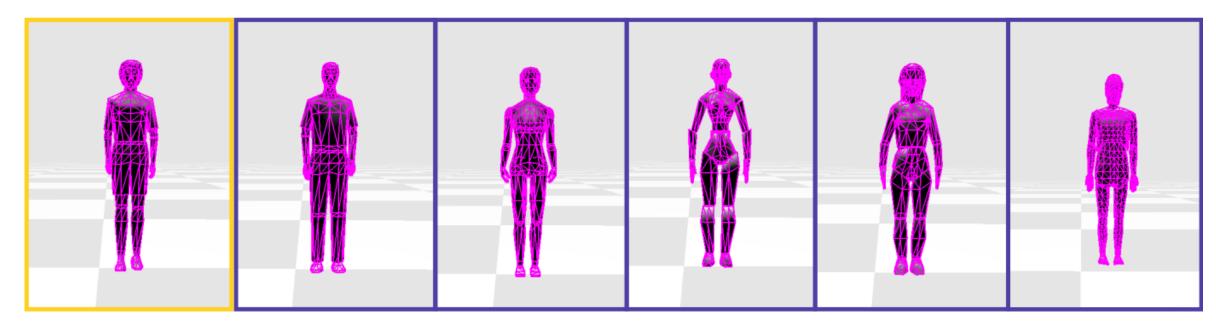
D3 = Sqrt(Area) of random triangle

D4 = Cuberoot of volume of tetrahedron

Good Query Results

Query

First 5 results



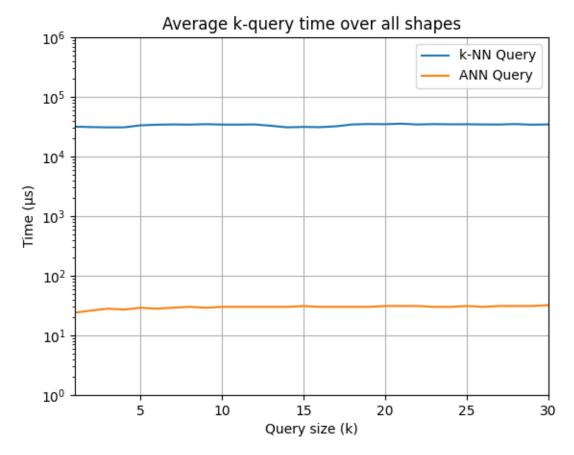
Bad Query Results

Query

First 5 results



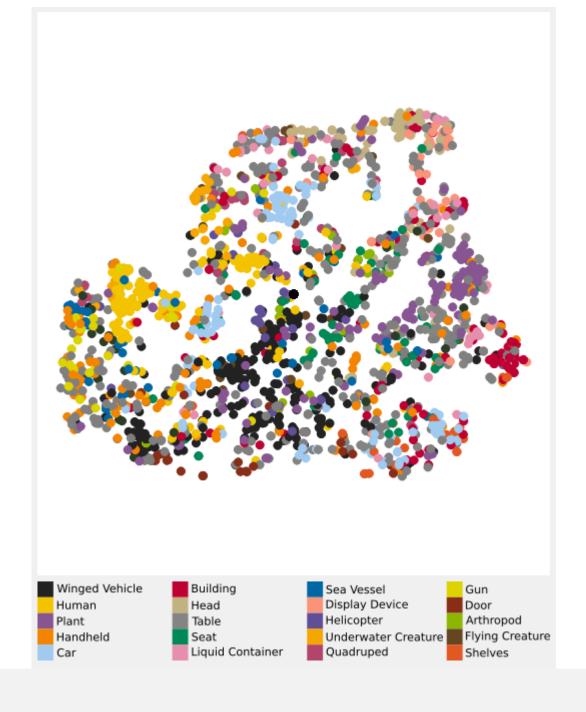
Scalability



Computed on

Intel® Core™ i7-4790K

Nearest Neighbor Search



Dimensionality Reduction

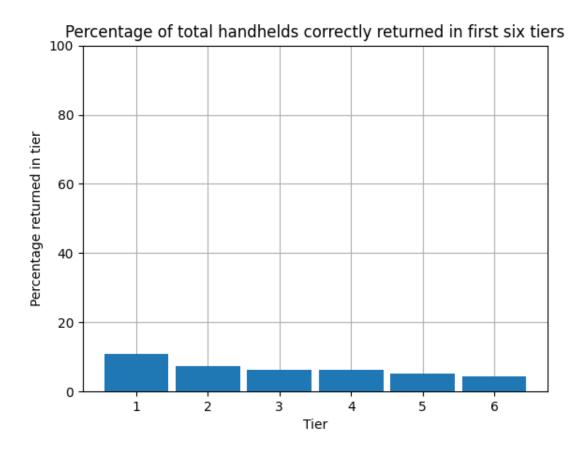
- Linear GPGPU t-SNE Embedding
 - 2000 Iterations
 - 30 Perplexity
 - Computed on-the-fly in 1 second

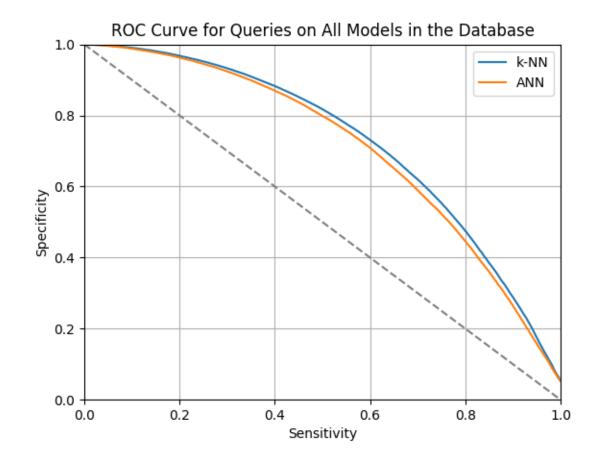
Evaluation

Human

Percentage of total humans correctly returned in first six tiers 100 80 Percentage returned in tier 20 Tier

Handheld





Evaluation

- ROC curve
 - Computed for all query sizes
 - Averaged over all possible queries

Demo