# Numerical Methods for Time-Dependent PDEs

### Test (tentamen): WISL602

June 12, 2019: 10:00-13:00

# • Question 1 (10 points)

Classify the PDE:  $\alpha u_{tt} + \beta u_t + \gamma u_{xx} - x^2 u_x = \sin(x)e^{-t}$ with  $\alpha \ge 0, \ \beta \in \mathbb{R}, \ \gamma \ne 0$ . (hyperbolic, parabolic, elliptic?)

# Question 2 (15 points)

Consider the ODE:  $\dot{y}(t) = f(y(t)).$ 

a) Find the *stability* polynomial  $\pi(z;\zeta)$  for the *Leapfrog* method:

$$\frac{y^{n+1} - y^{n-1}}{2\Delta t} = f(y^n).$$

b) Find the stability function R(z) for the 3/8-rule RK-method (Kutta, 1901):

$$\begin{cases} k_1 = \Delta t \ f(y^n), \\ k_2 = \Delta t \ f(y^n + \frac{1}{3}k_1), \\ k_3 = \Delta t \ f(y^n - \frac{1}{3}k_1 + k_2, \\ k_4 = \Delta t \ f(y^n + k_1 - k_2 + k_3), \\ y^{n+1} = y^n + \frac{1}{8}[k_1 + 3k_2 + 3k_3 + k_4]. \end{cases}$$

c) What does *zero-stability* mean and why is this an important concept? What is the role of R(z) in terms of *stability regions* and stability properties of time-integration methods?

# Question 3 (15 points)

Consider the *advection* equation:  $u_t + c \ u_x = 0, \ c \in \mathbb{R}.$ 

a) Show, using *Von Neumann stability analysis*, that the forward (in space and time) scheme

$$u_j^{n+1} = (1 + \frac{c\Delta t}{\Delta x})u_j^n - \frac{c\Delta t}{\Delta x}u_{j+1}^n$$

is always <u>un</u>stable for c > 0.

b) Work out the *local truncation error* of this scheme and show that the method is first-order accurate. What happens in the special case  $\frac{c\Delta t}{\Delta x} = -1$  and why?<sup>2</sup>

<sup>&</sup>lt;sup>1</sup>It is convenient to define  $z = \lambda \Delta t$ .

 $<sup>^2 \</sup>rm Check$  this for the second-order term only, but predict what could happen for higher-order terms in the error.

### Question 4 (25 points)

Consider the PDE:

$$\begin{cases} u_t = \alpha \ u_{xxxx}, \ \alpha \in \mathbb{R}, \ x \in [0,1], \ t > 0, \\ u(0,t) = u(1,t) = u_x(0,t) = u_x(1,t) = 0, \ u(x,0) = u_0(x) \end{cases}$$

a) Use the method of undetermined coefficients to find a second-order accurate approximation of  $u_{xxxx}$  at the grid point  $x_j = j\Delta x$ , j = 0, 1, ..., J with  $\Delta x = \frac{1}{J}$  of the form (determine the constants A and B):

$$\frac{Au_{j+2} + Bu_{j+1} + 6u_j - 4u_{j-1} + u_{j-2}}{(\Delta x)^4}.$$

b) Apply the first step in the (vertical) *Method-Of-Lines* (M.O.L.) and give the resulting system of ODEs in terms of the matrix  $\mathcal{D}_{4c}$  (representing  $u_{xxxx}$ ) and the solution vector  $\vec{u}$ . Discuss how you include the four *boundary conditions* in the matrix  $\mathcal{D}_{4c}$ .

c) For the second step in M.O.L. we could use: i) Euler-Forward (EF), ii) Euler-Backward (EB) or iii) the Trapezoidal method (TM). Sketch the *computational stencil* of the full space-time finite-difference method for the three cases.

d) Which stability criterion of the form  $-\alpha \frac{(\Delta t)^p}{(\Delta x)^q} \leq C$  do you expect to hold for the method EF as time-integrator in the case  $\alpha < 0$ ? (specify the values of p and q, no calculations needed here)

e) It is given that the eigenvalues of the  $\mathcal{D}_{2c}$ -matrix (for  $u_{xx}$  at  $x_j$ ) are:

$$\lambda_j = \frac{2}{(\Delta x)^2} (\cos(j\pi\Delta x) - 1), \quad j = 1, ..., J - 1.$$

Discuss the effect of the value of  $\alpha \in \mathbb{R}$  on the eigenvalues distribution of  $\alpha \mathcal{D}_{4c}$  in the complex plane<sup>3</sup>, and on the numerical stability of EF, EB and TM.

### • Question 5 (10 points)

We apply a *finite element method* with *piecewise linear functions*, both as approximating and test functions, to discretize the damped wave equation:

$$u_{tt} + \beta u_t - \Delta u = 0, \ (x, y) \in [0, 1] \times [0, 1] \subset \mathbb{R}^2$$

with initial conditions  $u(x, y, 0) = u_0(x, y), u_t(x, y, 0) = v_0(x, y)$  and homogeneous Dirichlet boundary conditions.

<sup>&</sup>lt;sup>3</sup>You may use the fact that the eigenvectors of  $\mathcal{D}_{2c}$  and  $\mathcal{D}_{4c}$  are identical.

Give the resulting system of time-dependent ODEs in terms of matrices  $\mathcal{A}_1, \mathcal{A}_2, \mathcal{A}_3$ and solution vector  $\vec{u}$ , after the first step in the M.O.L..

Bonus (5 points): Describe the *structure* of the matrices  $A_1$ ,  $A_2$ ,  $A_3$  and, in particular, their *non-zero* elements.

# Question 6 (10 points)

a) Check that the *Leapfrog* method

$$\frac{y^{n+1} - y^{n-1}}{2\Delta t} = \sqrt{y^n}, \quad y^0 = 1, \ y^1 = \frac{1}{4}(\Delta t)^2 + \Delta t + 1$$

is an *exact* finite difference (FD) scheme for:  $\dot{y}(t) = \sqrt{y(t)}$  with y(0) = 1.

b) Give two important ingredients of a *nonstandard* FD scheme, when compared to a standard FD scheme.

### $\mathbf{Question} \ \mathbf{7} \ {}_{(15 \mathrm{\ points})}$

Consider the  $\theta$ -method for the ODE  $\dot{y} = f(t, y)$ :

$$y^{n+1} = y^n + \Delta t[\theta f(t^{n+1}, y^{n+1}) + (1-\theta)f(t^n, y^n)]$$

with parameter  $\theta \in [0, 1]$ .

a) Which values of  $\theta$  yield, respectively, Euler-Forward, Euler-Backward and the Trapezoidal method?

b) Give the order of approximation of the  $\theta$ -method (check the dependance on the value of  $\theta$ ).

c) For which values of  $\theta$ , do we obtain an *explicit*, and for which  $\theta$ , do we obtain an *implicit* method?

d) Give the stability function  $R_{\theta}(z)$  of the  $\theta$ -method.

e) Consider also two other stability functions:

$$R_2(z) = 1 + z + \frac{1}{2}z^2$$
 and  $R_3(z) = 1 + z + \frac{1}{2}z^2 + \frac{1}{6}z^3 + \frac{1}{24}z^4$ .

On the *next page* you find plots of six stability regions A), B), ..., F). Connect five of these plots to a stability function from the set {  $R_{\theta}, R_2, R_3$  } and specify  $\theta$ , if needed. Connect each plot to one time-integration method. The sixth, remaining, plot: which method belongs to this stability region? (no stability function should be given for this case)

