

Numerical Methods for Time-Dependent PDEs

Spring 2025

Exercises for Lecture 4

Consider the heat equation:

$$u_t = u_{xx}. \quad (1)$$

Exercise 4.1

Derive the Crank-Nicolson method for the heat equation (1) at the gridpoint $(x_i, t^{n+\frac{1}{2}})$:

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} = \frac{u_{i+1}^{n+1} - 2u_i^{n+1} + u_{i-1}^{n+1} + u_{i+1}^n - 2u_i^n + u_{i-1}^n}{2(\Delta x)^2}.$$

Exercise 4.2

Derive the DuFort-Frankel scheme and its error term for the heat equation (1).

Exercise 4.3

Sketch the computational stencil for the Crank-Nicolson method, the Leapfrog method and the DuFort-Frankel scheme, when applied to (1).

Exercise 4.4

Show that, for the particular choice of the stepsizes $\Delta t = \frac{(\Delta x)^2}{\sqrt{12}}$, the DuFort-Frankel scheme is second-order in time and fourth-order accurate in space (hint: expand the terms more carefully and use a relation between u_{tt} and u_{xxxx}).

Exercise 4.5

Show that the local truncation error τ for the Crank-Nicolson method is second-order in space and time, i.e. $\tau = \mathcal{O}((\Delta t)^2) + \mathcal{O}((\Delta x)^2)$ and compute the dominant term in τ .

Exercise 4.6

Suppose that an explicit (in time) finite difference method is used to approximate the heat equation. It can be written in the form:

$$\mathbf{u}^{n+1} = \mathcal{B}\mathbf{u}^n + \mathbf{b}^n,$$

with an $(M - 1) \times (M - 1)$ -matrix \mathcal{B} and righthand-side vector \mathbf{b}^n of length $M - 1$. If we apply the finite difference equations to the exact solution u_* we can write:

$$\mathbf{u}_*^{n+1} = \mathcal{B}\mathbf{u}_*^n + \mathbf{b}^n + \Delta t \boldsymbol{\tau}^n,$$

where $\boldsymbol{\tau}^n$ denotes the vector of local truncation errors in each grid point x_i at time level t^n . Define the global error at time $t = t^n$ by $\mathbf{E}^n = \mathbf{u}_*^n - \mathbf{u}^n$.

Show that, if \mathcal{B}^n (now as a power in n) is bounded for all Δt and indices n with $n\Delta t \leq T_{end}$ ('stability'), and if the method is consistent ($\boldsymbol{\tau}^n \rightarrow 0$, for $\Delta t \downarrow 0$), then the finite difference method is convergent: $\lim_{n \rightarrow \infty} \mathbf{E}^n = \mathbf{0}$.

Exercise 4.7

Show, using the Von Neumann-stability analysis, that the Crank-Nicolson method applied to the heat equation (1) is unconditionally stable.

Exercise 4.8

The same question as in exercise 4.7, but now for the DuFort-Frankel scheme applied to the heat equation (1).