

# Twenty years of collaboration...

Gerard's 65th birthday celebration

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# Twenty years of collaboration...



# Outline

Quadratic eigenvalue problems are no problem  
Utrecht 1994-1996

Relax to the max  
Toulouse 2002-2004

The subspaces are shrinking  
Delft 2005-

# Quadratic eigenvalue problems are no problem

UTRECHT

# Jacobi-Davidson

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- ▶ At that moment, there was very little research on the numerical solution of nonlinear eigenvalue problems (this has changed completely...).
- ▶ I asked Gerard if it was possible to use JD for this problem.
- ▶ The next day he gave me a manuscript of ten pages ...

## JD for nonlinear problem $F(\lambda)\mathbf{x} = 0$

a. **Start:**

Choose initial subspace  $\mathbf{V}$

b. **Repeat:**

(1) Compute desired eigenpair  $(\theta, y)$  from  $\mathbf{V}^* F(\theta) \mathbf{V} y = 0, \|y\| = 1$

(2) Compute  $\mathbf{u} \leftarrow \mathbf{V} y, \mathbf{r} \leftarrow F(\theta) \mathbf{u}$

(3) **Stop if** satisfied

(4)  $\mathbf{w} \leftarrow F'(\theta) \mathbf{u}$

(5) Solve  $(\mathbf{I} - \frac{\mathbf{u} \mathbf{w}^*}{\mathbf{w}^* \mathbf{u}}) F(\theta) (\mathbf{I} - \mathbf{u} \mathbf{u}^*) \mathbf{t} = -\mathbf{r}$

(6) Expand  $\mathbf{V}$ :  $\mathbf{V} \leftarrow \text{Ortho}([\mathbf{V} \mid \mathbf{t}])$ .

## Application: room acoustics

Propagation of sound:

$$\frac{1}{c^2} \frac{\partial^2 p}{\partial t^2} = \Delta p \quad \text{in } \Omega$$

$c$ : speed of sound,  $p$ : acoustic pressure

Boundary conditions:

- Reflecting wall:  $\frac{\partial p}{\partial n} = 0$
- Open wall (pressure release):  $p = 0$
- Absorbing wall:  $\frac{\partial p}{\partial n} = -\frac{1}{z} \frac{\partial p}{\partial t}$

$z$  is the (complex) impedance, may depend on frequency

# Analytical eigenproblem

Assume solution

$$p = \bar{p}e^{\lambda t}$$

with  $\lambda$  an analytical eigenvalue. Substitute in wave equation:

$$\frac{\lambda^2}{c^2}\bar{p} = \Delta\bar{p}$$

B.c. for absorbing wall:

$$\frac{\partial\bar{p}}{\partial n} = -\frac{\lambda}{z(\lambda)}\bar{p}$$

Eigenfrequencies:  $f = \text{Im}(\lambda)/2\pi$

## Discretization with FEM

Discretisation with the Finite Element method gives:

$$\mathbf{K}\mathbf{p} + \lambda\mathbf{C}(\lambda)\mathbf{p} + \lambda^2\mathbf{M}\mathbf{p} = \mathbf{0}$$

- ▶  $\mathbf{p}$ : Discretization of  $\bar{p}$
- ▶  $\lambda$ : Algebraic eigenvalue
- ▶  $\mathbf{K}$ : Stiffness matrix, discretization of  $-\Delta$
- ▶  $\mathbf{C}$ : Damping matrix, discretization of impedance condition
- ▶  $\mathbf{M}$ : Mass matrix, discretization of  $\frac{1}{c^2}$

## Example cube

- Domain:  $\Omega$  is  $4 \times 4 \times 4 \text{ m}^3$
- 5 reflecting walls
- 1 absorbing wall
- Soundspeed  $c = 340 \text{ m/s}$
- Impedance:  $z = (0.2 - 1.5i)c$   
(does not depend on frequency  $\rightarrow$  quadratic eigenproblem)
- Discretisation: linear tetrahedral elements
- Known analytical eigenvalue:  $\lambda = -5.19 + 217.5i$

## Results cube

- Grid:  $64 \times 64 \times 64 \times 5$  elements  $\rightarrow$  274,625 grid points
- Goal: eigenvalue closest to  $-5.19 + 217.5i$
- Selection of Ritz value closest to analytical eigenvalue
- Correction equation 'solved' with 30 GMRES steps
- Restart after 20 JD-iterations to save memory

Calculations performed on Cray T3D using 64 processors.  
Eigenvalue  $-5.20 + 217.5i$  converged after 33 JD-iterations.

Computing time: 93.4 seconds (20 years ago!!!)



Relax to the max

**TOULOUSE**

# Relaxation



## Relaxation strategies

Krylov methods allow the matrix-vector products to be computed to lower accuracy when the process starts to converge.

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We assume that an operation is available to compute the matvec in step  $j$  to precision  $\eta_j$ :

$$A_{\eta_j}(\mathbf{v}) = \mathbf{A}\mathbf{v} + \mathbf{g} \quad \text{with} \quad \|\mathbf{g}\| < \eta_j \|\mathbf{A}\| \|\mathbf{v}\|$$

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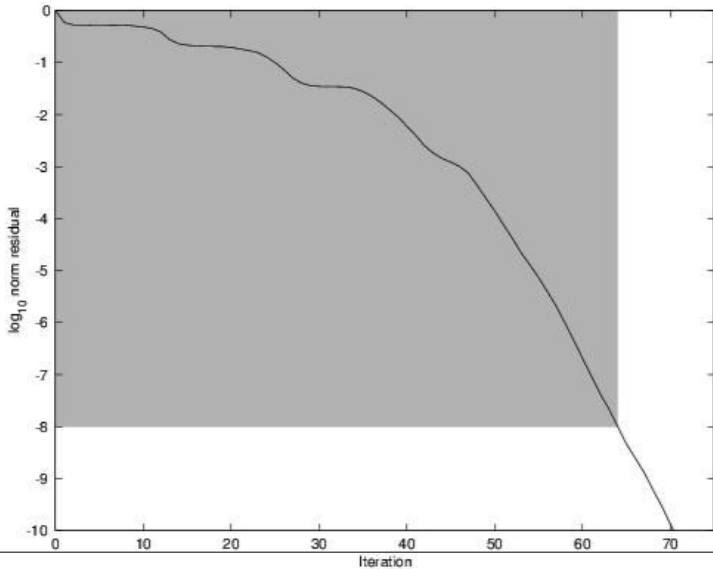
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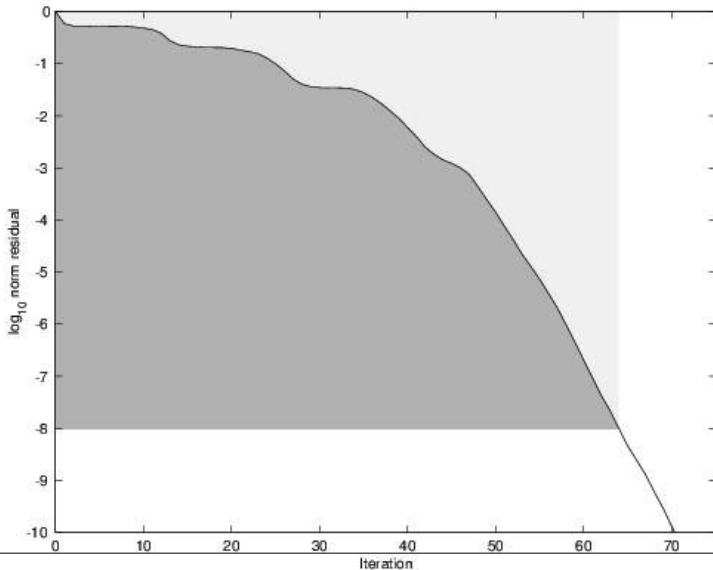
A simple relaxation strategy is to choose

$$\eta_j = \frac{\epsilon}{\|\mathbf{r}_j\|}$$

# No relaxation



# Relaxation



# Idea: use nested Krylov method

- ▶ Outer loop
  - ▶ Aim for desired accuracy
  - ▶ Use relaxation
- ▶ Inner loop (preconditioner)
  - ▶ Aim for low accuracy
  - ▶ Use relaxation

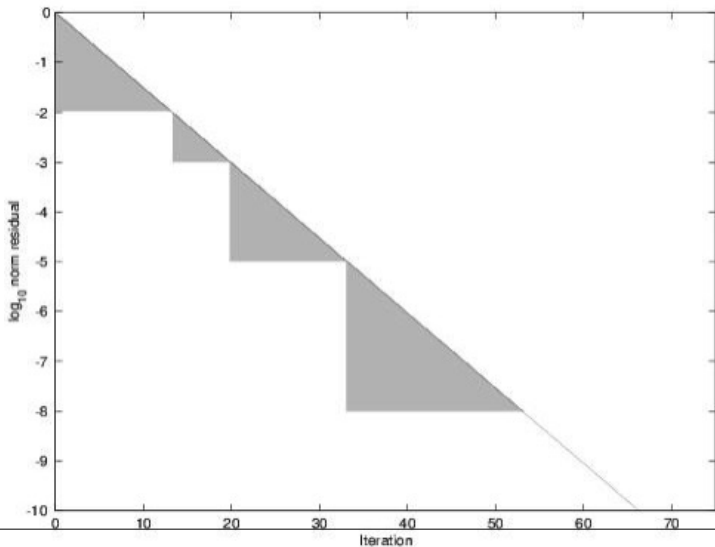


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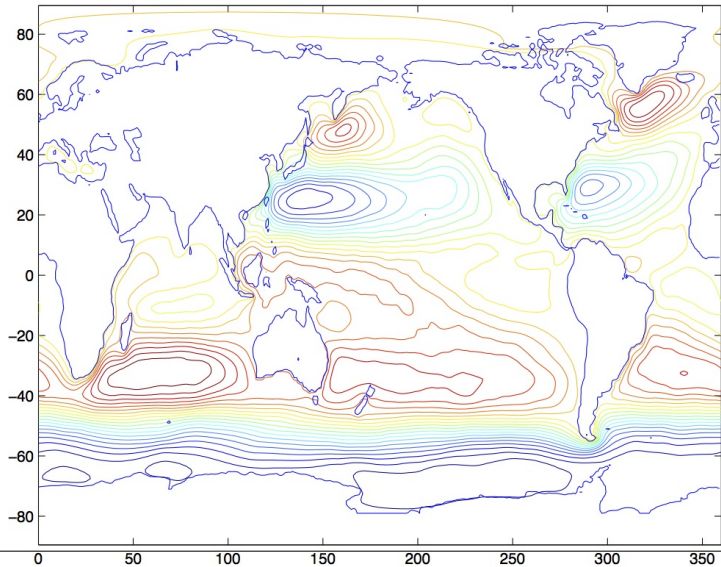
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Almost all matrix-vector products can be performed at low accuracy!

# Relax to the max



## Example: ocean circulation



## Discrete ocean problem

Global system:

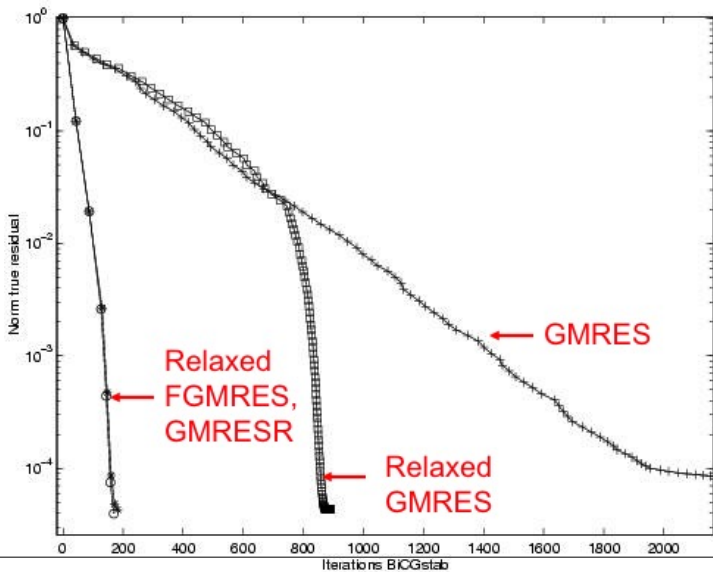
$$\begin{pmatrix} r\mathbf{L} - \mathbf{C} & A\bar{\mathbf{L}} \\ -\bar{\mathbf{L}}^H & \mathbf{M} \end{pmatrix} \begin{pmatrix} \bar{\psi} \\ \bar{\zeta} \end{pmatrix} = \begin{pmatrix} \mathbf{f} \\ \mathbf{0} \end{pmatrix}$$

Schur complement for the vorticity:

$$(\mathbf{M} + A\bar{\mathbf{L}}^H(r\mathbf{L} - \mathbf{C})^{-1}\bar{\mathbf{L}})\bar{\zeta} = \bar{\mathbf{L}}^H(r\mathbf{L} - \mathbf{C})^{-1}\mathbf{f}$$

- ▶ Action of  $(r\mathbf{L} - \mathbf{C})^{-1}$  is approximated by preconditioned Bi-CGSTAB.
- ▶ Accuracy of Bi-CGSTAB, and therefore of the multiplication with the Schur complement, can be controlled.

# Relax to the max



# The subspaces are shrinking

**DELFT**

# The subspaces are shrinking (using IDR)



## Two theorems

### Theorem (IDR)

Let  $\mathbf{P} = [\mathbf{p}_1, \dots, \mathbf{p}_s]$  be an  $n \times s$  matrix and let  $(\mu_j)$  be a sequence in  $\mathbb{C}$ . With  $\mathcal{G}_0 \equiv \mathcal{C}^n$ , define,

$$\mathcal{G}_{j+1} \equiv (\mu_j \mathbf{I} - \mathbf{A})(\mathcal{G}_j \cap \mathbf{P}^\perp) \quad (j = 0, 1, \dots).$$

If  $\mathbf{P}^\perp$  does not contain an eigenvector of  $\mathbf{A}$ , then, for all  $j = 0, 1, \dots$ , we have that

1)  $\mathcal{G}_{j+1} \subset \mathcal{G}_j$ , and 2)  $\dim \mathcal{G}_{j+1} < \dim \mathcal{G}_j$  unless  $\mathcal{G}_j = \mathbf{0}$ .



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### Theorem (BLOCK-KRYLOV)

Let  $\mathbf{P}$ ,  $(\mu_j)$  and  $\mathcal{G}_j$  be as above. Consider the polynomial  $p$  of degree  $j$  given by  $p(\lambda) \equiv \prod_{i=1}^j (\mu_i - \lambda)$  ( $\lambda \in \mathbb{C}$ ). Then

$$\mathcal{G}_j = \{p_j(\mathbf{A})\mathbf{v} \mid \mathbf{v} \perp \mathcal{K}_j(\mathbf{A}^H, \mathbf{P})\}.$$

## IDRStab

Can other polynomials than products of linear factors

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Yes, by combining several dimension reductions steps it is possible to construct higher order factors.

The name of this method is **IDRStab**. (SISC 2010)

# This is the moment Gerard figured it out



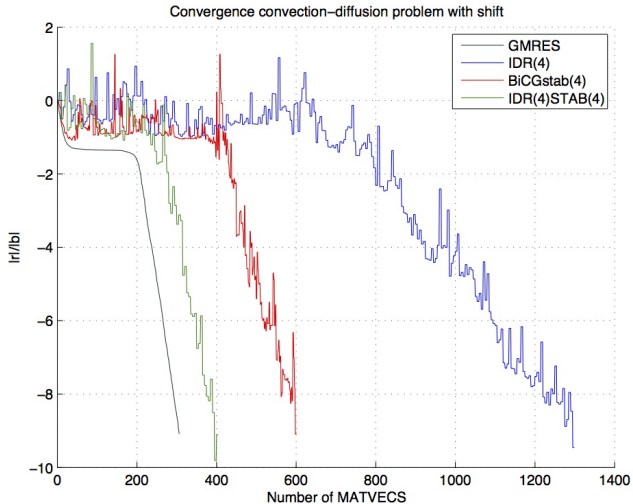
## Example

Convection-diffusion problem with shift on unit square:

$$-u_{xx} - u_{yy} + 1000(xu_x + yu_y) + 10u = f .$$

- ▶ Dirichlet conditions
- ▶ Discretised with the finite volume method on a  $65 \times 65$  grid
- ▶ The right-hand side vector such that the solution is one.

# Convergence of IDRStab



# Numerical Linear Algebra course

- ▶ For several years we have taught together the Mastermath course on Numerical Linear Algebra

# Gerard can teach Numerical Linear Algebra to any audience

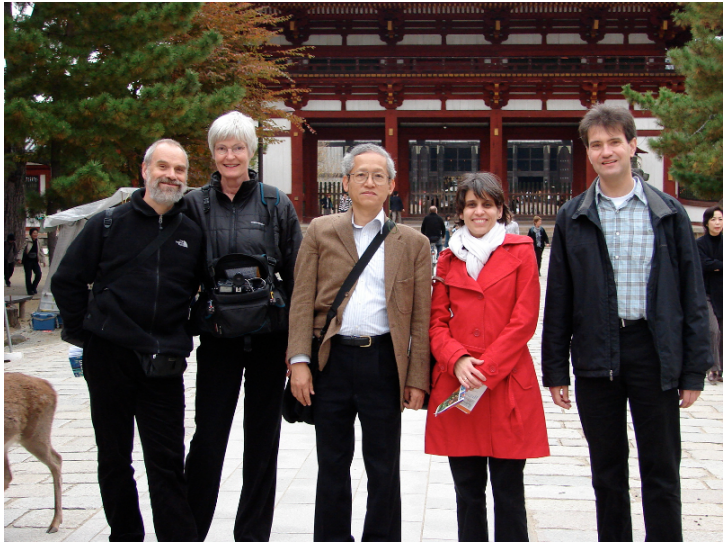




I do my best ...



# To conclude: nice memories of Japan



# Gerard can find the way in any language



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Gerard: CONGRATULATIONS!