

PDE (x and t)

or

ODE
(x or t)

$\mathcal{F}$ -transformation

with respect
to x (PDE)

ODE (w
and t)

Algebraic
equation (w)

direct?
(possible?)

solution
(x, t)

$^{-1}$
 $\mathcal{F}$ -transformation

with respect
to w ("PDE-case")

solve

(w is a
parameter)

solution $\left\langle \begin{matrix} (w, t) \\ w \end{matrix} \right.$

sometimes an " $\int$ " remains in the expression

sometimes, using a $\mathcal{F}$ -property, the " $\int$ "

can be resolved to an "exact" formula

or $\sum$ solution

Applications of $\mathcal{F}$ -transformation:

- * signals
 - sound
 - images
 - measurements
- * solving differential equations
- * ...

now:

Laplace transformation: $\mathcal{L}$

applications:

- * engineering
 - electric circuits
 - digital signals
 - nuclear physics
- * solving differential equations
- * ...

Intermezzo

(3)

The Euler-Gamma function
("Gamma-function")

for $x > 0$ define: $\Gamma(x) = \int_0^{\infty} t^{x-1} e^{-t} dt$

this integral is finite for all $x > 0$

Remember the "factorial":

$$1! = 1$$

$$2! = 2 \cdot 1 = 2 = 2 \cdot 1!$$

$$3! = 3 \cdot 2 \cdot 1 = 6 = 3 \cdot 2!$$

$$4! = 4 \cdot 3 \cdot 2 \cdot 1 = 24 = 4 \cdot 3!$$

$$5! = 5 \cdot 4 \cdot 3 \cdot 2 \cdot 1 = 120 = 5 \cdot 4!$$

⋮

etcetera

$$\left. \begin{array}{l} 1! = 1 \\ 2! = 2 \cdot 1 = 2 = 2 \cdot 1! \\ 3! = 3 \cdot 2 \cdot 1 = 6 = 3 \cdot 2! \\ 4! = 4 \cdot 3 \cdot 2 \cdot 1 = 24 = 4 \cdot 3! \\ 5! = 5 \cdot 4 \cdot 3 \cdot 2 \cdot 1 = 120 = 5 \cdot 4! \\ \vdots \\ \text{etcetera} \end{array} \right\} n! = \prod_{k=1}^n k$$

"product" ↙

$$= 1 \cdot 2 \cdot 3 \cdot 4 \cdot \dots \cdot (n-1) \cdot n$$

$$\Rightarrow \text{property: } (n+1)! = (n+1) \cdot n!$$

for integer values of n

"define": $0! = 1$

Note that:

$$\begin{aligned}
 \Gamma(x+1) &= \int_0^{\infty} t^{(x+1)-1} e^{-t} dt \\
 &= \int_0^{\infty} t^x e^{-t} dt \\
 &\stackrel{\text{integration by parts}}{=} \left[\underbrace{-t^x e^{-t}}_{=0} \right]_{t=0}^{t=\infty} - \int_0^{\infty} \underbrace{-x t^{x-1} e^{-t}}_{+} dt \\
 &= \int_0^{\infty} x t^{x-1} e^{-t} dt \\
 &= x \int_0^{\infty} \underbrace{t^{x-1} e^{-t}}_{=\Gamma(x)} dt = x \cdot \Gamma(x)
 \end{aligned}$$

Calculate:

$$\Gamma(1) = \int_0^{\infty} \underbrace{t^0}_{=1} e^{-t} dt = -e^{-t} \Big|_{t=0}^{t=\infty} = 0 + 1 = 1$$

(---) = 0!

$$\Gamma(2) = 1 \cdot \Gamma(1) = 1 = 1!$$

$$\Gamma(3) = 2 \cdot \Gamma(2) = 2 \cdot 1 = 2!$$

$$\Gamma(4) = 3 \cdot \Gamma(3) = 3 \cdot 2 = 3!$$

⋮

etcetera

⇒

$$\Gamma(n+1) = n!$$

$n = 0, 1, 2, 3, \dots$

the Gamma-function is a generalized factorial !!!

(5)

what is $\Gamma(\frac{1}{2})$?

$$\Gamma(\frac{1}{2}) = \int_0^{\infty} t^{-\frac{1}{2}} e^{-t} dt = 2 \cdot \int_0^{\infty} \frac{1}{u} e^{-u^2} u du$$

change of variables

$$t = u^2$$

$$dt = 2u du$$

$$t^{-1/2} = (u^2)^{-1/2} = \frac{1}{u}$$

$$= 2 \int_0^{\infty} e^{-u^2} du$$

$$= 2 \cdot \frac{1}{2} \sqrt{\pi}$$

see before

$$= \sqrt{\pi} = \dots$$

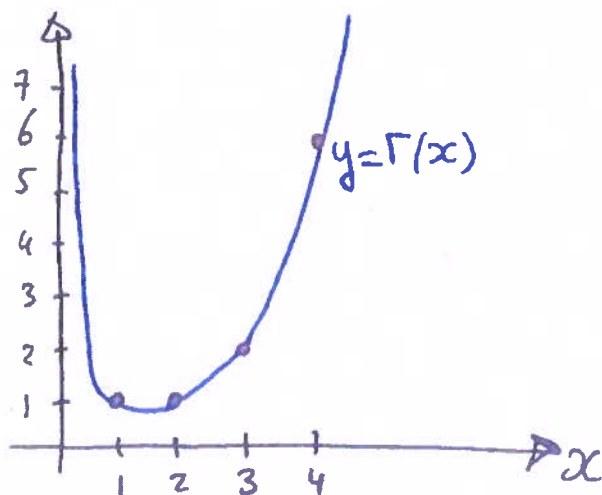
$$\sim \left(\frac{1}{2}\right)!$$

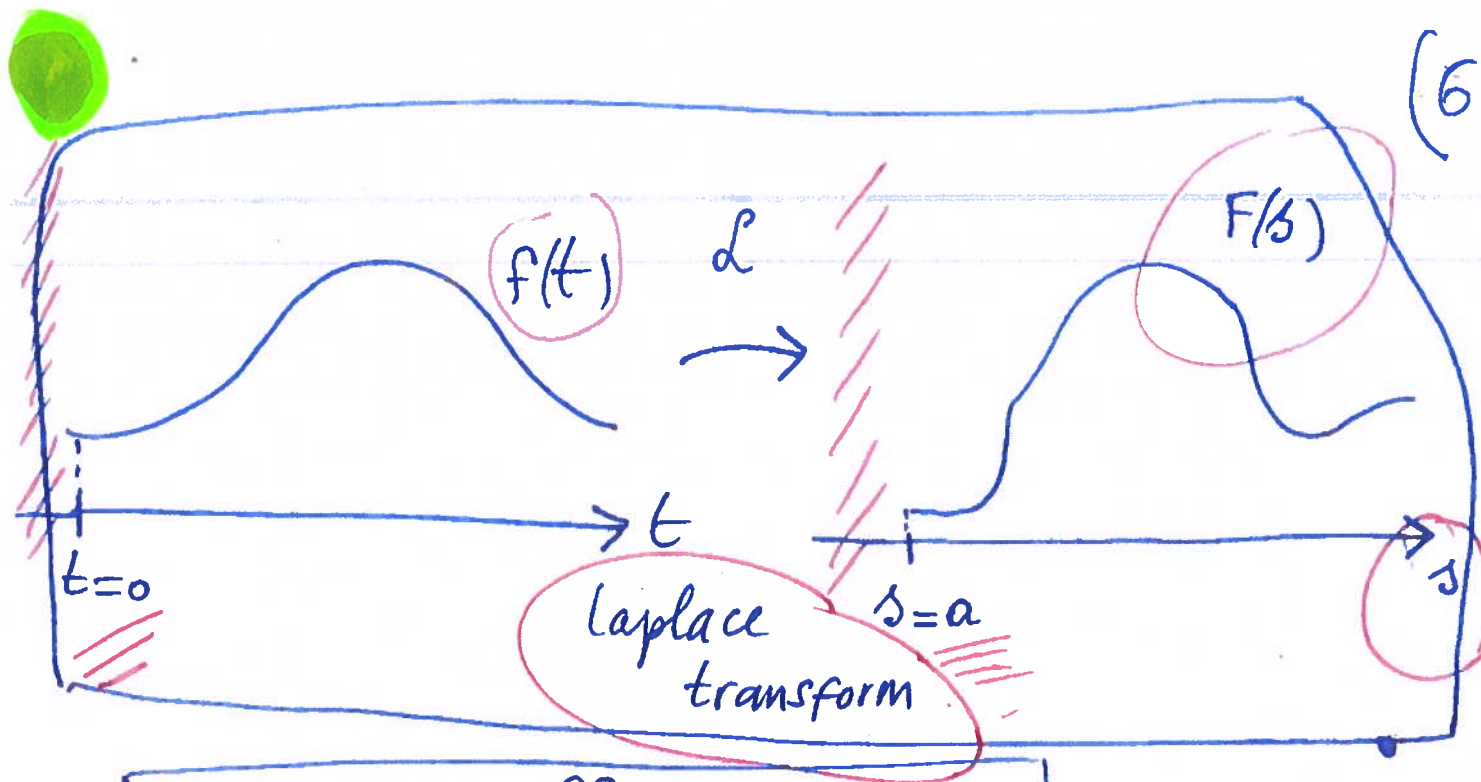
$$\Gamma(\frac{3}{2}) = \frac{1}{2} \cdot \Gamma(\frac{1}{2}) = \frac{1}{2} \sqrt{\pi} = \dots$$

$$\sim \left(\frac{3}{2}\right)! \quad \Gamma(\frac{5}{2}) = \frac{3}{2} \cdot \Gamma(\frac{3}{2}) = \frac{3}{2} \cdot \frac{1}{2} \sqrt{\pi} = \frac{3}{4} \sqrt{\pi} = \dots$$

etcetera ...

Graph of $\Gamma(x)$ for $x > 0$:





$$\underbrace{\mathcal{L}(f(t))}_{\substack{\text{a function} \\ \text{of } s}} \stackrel{\text{def.}}{=} \int_0^{\infty} \underbrace{e^{-st}}_{\substack{\text{the kernel} \\ \text{of the transformation}}} f(t) dt = F(s)$$

$s > a > 0$

$\mathcal{L}(f(t))(s)$

beta -- (check the "w" in the F-transform)

Example 1 $f(t) = c$ ← constant function

$$\Rightarrow \mathcal{L}(c) = \int_0^{\infty} e^{-st} \cdot c \, dt = c \int_0^{\infty} e^{-st} \, dt = c \frac{1}{-s} e^{-st} \Big|_{t=0}^{t=\infty}$$

$\frac{c}{-s} [0 - 1] = \frac{c}{s} \quad (s > 0)$

$s > 0$

Example 2

$$f(t) = t$$

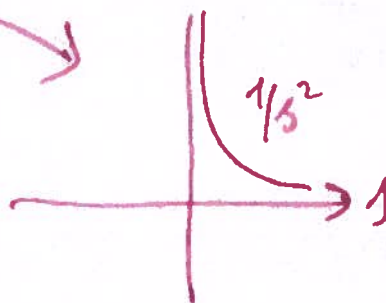
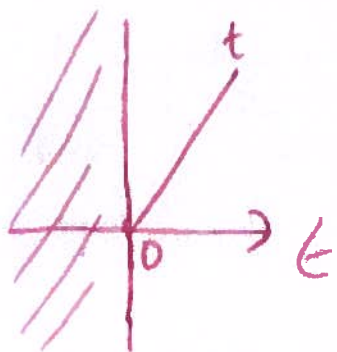
linear function

(7)

$$\Rightarrow \mathcal{L}(t) = \int_0^{\infty} e^{-st} t dt = \left[-\frac{t}{s} e^{-st} \right]_{t=0}^{t=\infty} + \int_0^{\infty} \frac{1}{s} e^{-st} dt$$

integration by parts

$$s > 0 \Rightarrow \left[\underbrace{0}_{=0} + \underbrace{0}_{=0} \right] + \frac{1}{s} \int_0^{\infty} e^{-st} dt$$



$$= -\frac{1}{s^2} \left[e^{-st} \right]_{t=0}^{t=\infty} = -\frac{1}{s^2} [0 - 1] = \frac{1}{s^2} \quad (s > 0)$$

Example 3

$$f(t) = e^{kt}$$

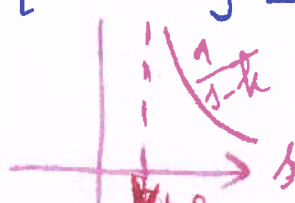
k : a given positive constant

$$\Rightarrow \mathcal{L}(e^{kt}) = \int_0^{\infty} e^{-st} \cdot e^{kt} dt = \int_0^{\infty} e^{-(s-k)t} dt$$

now important

$$s > k \Rightarrow -\frac{1}{s-k} e^{-(s-k)t} \bigg|_{t=0}^{t=\infty}$$

$$= -\frac{1}{s-k} [0 - 1] = \frac{1}{s-k}$$



Example 4

$$f(t) = \sin(\alpha t)$$

$$\alpha \in \mathbb{R}$$

(8)

$$g(t) = \cos(\alpha t)$$

remember:

$$e^{i\alpha t} = \underbrace{\cos(\alpha t)}_{\text{Re}(\cdot)} + i \underbrace{\sin(\alpha t)}_{\text{Im}(\cdot)}$$

$$f(t) = \text{Im}(e^{i\alpha t})$$

$$g(t) = \text{Re}(e^{i\alpha t})$$

just calculated:

in example 3

$$\mathcal{L}(e^{kt}) = \frac{1}{s-k}$$

$$\Rightarrow \mathcal{L}(e^{i\alpha t}) = \frac{1}{s-i\alpha}, \quad s > 0$$

take
 $k = i\alpha$

$$= \frac{s+i\alpha}{(s+i\alpha)(s-i\alpha)} = \frac{s+i\alpha}{s^2+\alpha^2}, \quad s > 0$$

$$= \frac{s}{s^2+\alpha^2} + i \frac{\alpha}{s^2+\alpha^2}$$

$= \text{Re}(\mathcal{L}(e^{i\alpha t})) \quad = \text{Im}(\mathcal{L}(e^{i\alpha t}))$

$$\Rightarrow \mathcal{L}(\sin(\alpha t)) = \frac{\alpha}{s^2+\alpha^2}, \quad s > 0$$

$$\mathcal{L}(\cos(\alpha t)) = \frac{s}{s^2+\alpha^2}, \quad s > 0$$

this calculation

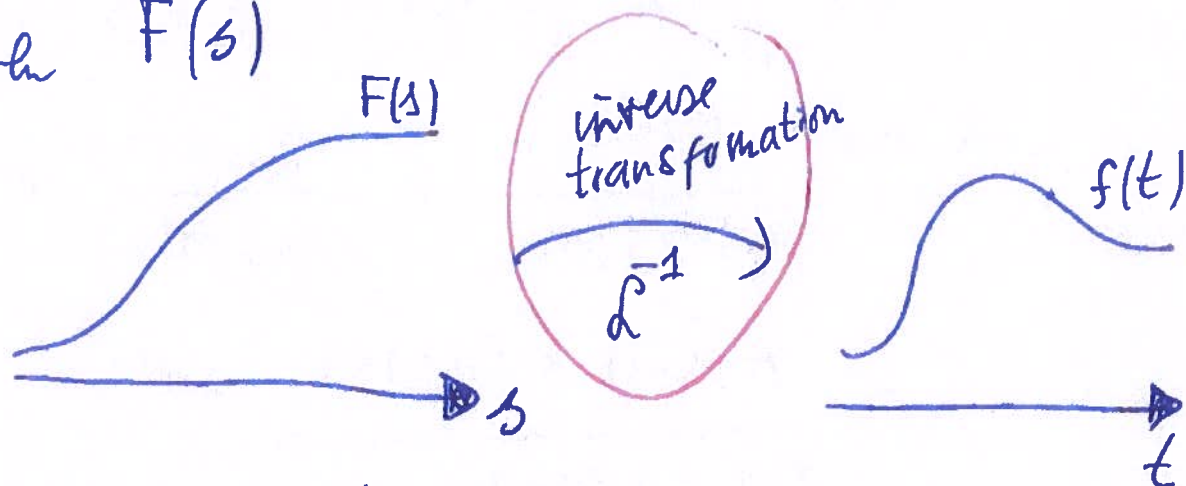
Can also be done "directly"

via integration by parts ----

Inverse Laplace transform

(9)

Given $F(s)$



* Both L and L^{-1} are linear ↗ this can be checked very easily

example 1)

we have $L(e^{kt}) = \frac{1}{s-k}$
 $\Rightarrow L^{-1}\left(\frac{1}{s-k}\right) = e^{kt}$

(see before)

"create
(→ table)"

example 2) $L^{-1}\left(\frac{1}{(s+3)(s-2)}\right) = ?$

(*) ↗ "breaksplitzen"

use partial fractions.

see later

write $\frac{1}{(s+3)(s-2)} = \frac{-1/5}{s+3} + \frac{1/5}{s-2}$

↗ useful, since we "understand" these functions

how?

$$\frac{1}{(s+3)(s-2)} = \frac{A}{s+3} + \frac{B}{s-2}$$

(10)

and find appropriate A & B values

work out: $\frac{A(s-2)}{(s-2)(s+3)} + \frac{B(s+3)}{(s+3)(s-2)}$ (multiply)

$$= \frac{A(s-2) + B(s+3)}{(s-2)(s+3)}$$
 (merge)

$$= \frac{(A+B)s + 3B - 2A}{(s-2)(s+3)}$$
 (re-arrange)

* "must be" $\frac{0s + 1}{(s-2)(s+3)}$ (set ...)

$$\Rightarrow \begin{cases} A+B=0 \\ 3B-2A=1 \end{cases} \xrightarrow{\text{solve}} \begin{cases} B=-A \\ -5A=1 \end{cases}$$

two equations with two unknowns

S

$$\begin{aligned} A &= -\frac{1}{5} \\ B &= \frac{1}{5} \end{aligned}$$

We know (from earlier calculations (11)
or from supplied table/formula sheet)

that

$$\mathcal{L}(e^{-kt}) = \frac{1}{s+k} \Rightarrow \mathcal{L}^{-1}\left(\frac{1}{s+k}\right) = e^{-kt}$$

use this
information
in our
formula

$$\mathcal{L}^{-1}\left(\frac{1}{(s+3)(s-2)}\right) = \mathcal{L}^{-1}\left(\frac{-1/5}{s+3} + \frac{1/5}{s-2}\right)$$

Linearity of $\mathcal{L}^{-1}$

$$= -\frac{1}{5} \mathcal{L}^{-1}\left(\frac{1}{s+3}\right) + \frac{1}{5} \mathcal{L}^{-1}\left(\frac{1}{s-2}\right)$$

$$= -\frac{1}{5} e^{-3t} + \frac{1}{5} e^{+2t}$$

"table" "table"

examples)

$$\mathcal{L}^{-1}\left(\frac{s+1}{s^2(s^2+9)}\right)$$

"breukspitzen"

$$\frac{s+1}{s^2(s^2+9)} = \frac{A}{s} + \frac{B}{s^2} + \frac{C(s+1)}{s^2+9}$$

why this one?

how and why?

work out (multiply) and solve for A, B, C

$$\Rightarrow A = 1/9, B = 1/9, C = 1/9$$

three equations with three unknowns

$$\Rightarrow \mathcal{L}^{-1}(\dots) = \frac{1}{9} + \frac{1}{9}t - \frac{1}{9} \cos(3t) - \frac{1}{27} \sin(3t)$$

Properties of Laplace transform

(12)

Linearity

$$\begin{aligned} \mathcal{L}(a f(t) + b g(t)) \\ = a \cdot \mathcal{L}(f(t)) + b \cdot \mathcal{L}(g(t)) \end{aligned}$$

example 1

$$\mathcal{L}(3t + 2e^{3t})$$

$$= 3 \cdot \mathcal{L}(t) + 2 \cdot \mathcal{L}(e^{3t})$$

$$= 3 \cdot \frac{1}{s^2} + 2 \cdot \frac{1}{s-3}$$

$(s > 0)$ $(s > 3)$ $\underline{s > 3}$

example 2

$$\mathcal{L}(5 - 3t + 4 \sin(2t) - 6e^{4t})$$

$$= \mathcal{L}(5) - 3 \mathcal{L}(t) + 4 \mathcal{L}(\sin(2t)) - 6 \mathcal{L}(e^{4t})$$

$$= \frac{5}{s} - 3 \cdot \frac{1}{s^2} + 4 \cdot \frac{2}{s^2 + 4} - 6 \cdot \frac{1}{s-4}$$

$(s > 0)$ $(s > 0)$ $(s > 0)$ $(s > 4)$ $\underline{s > 4}$

see before

Shift theorem

$$\mathcal{L}(e^{at} f(t)) = F(s-a) \quad \text{with } F(s) = \mathcal{L}(f(t))$$

$$s > \sigma$$

$$s > \sigma + a$$

example 1

$$\mathcal{L}(te^{-2t})$$

we know: $\mathcal{L}(t) = F(s) = \frac{1}{s^2}$, $s > 0$ ^{TABLE}

$$\Rightarrow \mathcal{L}(te^{-2t}) = F(s+2) = \frac{1}{(s+2)^2}, \quad s > -2$$

(a=-2)

example 2

$$\mathcal{L}(e^{-3t} \sin(2t))$$

we know: $\mathcal{L}(\sin(2t)) = F(s) = \frac{2}{s^2+4}$, $s > 0$ ^{TABLE}

$$\Rightarrow \mathcal{L}(e^{-3t} \sin(2t)) = F(s+3) = \frac{2}{(s+3)^2+4} = \frac{2}{s^2+6s+13}$$

(a=-3)

$$s > -3$$

derivative of a transform

if $F(s) = \mathcal{L}(f(t))$, $s > \sigma$

then $\mathcal{L}(t^n f(t)) = (-1)^n \frac{d^n F(s)}{ds^n}$, $s > \sigma$

example 1

we know

$$\mathcal{L}(\sin(3t)) = F(s) = \frac{3}{s^2 + 9}, \quad s > 0$$

$$\Rightarrow \mathcal{L}(t \sin(3t)) = (-1)^1 \frac{dF(s)}{ds},$$

$(n=1)$

$$= - \frac{dF(s)}{ds} = \frac{6s}{(s^2 + 9)^2}, \quad s > 0$$

example 2

we know

$$\mathcal{L}(e^t) = F(s) = \frac{1}{s-1}, \quad s > 1$$

check!

$$\Rightarrow \mathcal{L}(t^2 e^t) = (-1)^2 \frac{d^2 F(s)}{ds^2} = \frac{d^2}{ds^2} \left(\frac{1}{s-1} \right)$$

$(n=2)$

$$= - \frac{d}{ds} \left(\frac{1}{(s-1)^2} \right)$$

$$= \frac{2}{(s-1)^3}, \quad s > 1$$

proof for $n=1$: $\frac{d}{ds} [\mathcal{L}f(t)(s)] = \frac{d}{ds} \int_0^\infty f(t) e^{-st} dt = \int_0^\infty f(t) \frac{d}{ds} (e^{-st}) dt$
 similar for $n=2, 3, \dots$
 $= - \int_0^\infty t f(t) e^{-st} dt = - \mathcal{L}(t f(t))(s)$

partial integreren

Transforms of derivatives

$$\mathcal{L}(f'(t)) \stackrel{\text{def}}{=} \int_0^{\infty} f'(t) e^{-st} dt = \left[f(t) e^{-st} \right]_{t=0}^{t=\infty} + s \int_0^{\infty} f(t) e^{-st} dt$$

integration by parts

$$= [0 - f(0)] = -f(0) + s \cdot \mathcal{L}(f(t))$$

$$= -f(0) + s \cdot \mathcal{L}(f(t))$$

$$= -f(0) + s \cdot F(s)$$

$$\mathcal{L}(f''(t)) \stackrel{\text{def}}{=} \int_0^{\infty} f''(t) e^{-st} dt = \left[e^{-st} f'(t) \right]_{t=0}^{t=\infty} + s \int_0^{\infty} f'(t) e^{-st} dt$$

integr. by parts

$$= -f'(0)$$

$$= -f'(0) + s \cdot \mathcal{L}(f'(t))$$

$$= -f'(0) + s \cdot (-f(0) + s F(s))$$

above

$$= -f'(0) - s f(0) + s^2 F(s)$$

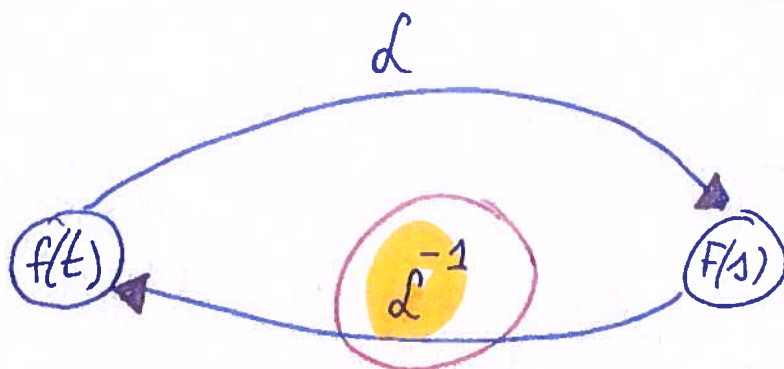
gaan we
gebruiken
om Dren
op de Dors!

etcetera

$$\mathcal{L}(f^{(n)}(t)) = s^n F(s) - \sum_{i=1}^n s^{i-1} f^{(i-1)}(0)$$

 $n = 1, 2, 3, \dots$

Inverse transform



example 1

$$\text{if } L(e^{at}) = \frac{1}{s-a}$$

$$\text{then } L^{-1}\left(\frac{1}{s-a}\right) = e^{at}$$

example 2

$$\text{if } L(\sin(\omega t)) = \frac{\omega}{s^2 + \omega^2}$$

$$\text{then } L^{-1}\left(\frac{\omega}{s^2 + \omega^2}\right) = \sin(\omega t)$$

etcetera

L is linear

$$L^{-1} \text{ is linear as well: } L^{-1}(\alpha F(s) + \beta G(s)) \\ = \alpha L^{-1}(F(s)) + \beta L^{-1}(G(s))$$

("breaksplitten")

(17)

Explanation



partial fractions

Rule 1

(teller)

the numerator must be of at least ^{noemenr} one degree less than the denominator (otherwise this does not work)

Rule 2

for each linear factor $ax+b$ in the denominator, there is a partial fraction of the form $\frac{A}{ax+b}$ (A constant)

rules ok

degrees

example:

$3x$

$(2x+1)(x+4)$

A

$2x+1$

B

$x+4$

$$\begin{cases} A = -\frac{3}{7} \\ B = \frac{12}{7} \end{cases}$$

Rule 3

if a linear factor is repeated n times in the denominator, there will be n corresponding partial fractions with degree 1 to n

example: $n=4$

$5x^3+7x-9$

$(x+1)^4$

four

A

$x+1$

B

$(x+1)^2$

C

$(x+1)^3$

D

$(x+1)^4$

degree 1

degree 2

degree 3

degree 4

rules ok

degree 3

degree 4

$n=2$

$x+5$

$(x+3)^2$

A

$x+3$

B

$(x+3)^2$

$$\begin{cases} A = 1 \\ B = 2 \end{cases}$$

$n=3$

$2x^2-3$

$(x-1)^3(x+1)$

A

$x-1$

B

$(x-1)^2$

C

$(x-1)^3$

D

$x+1$

$n=1$

$$\begin{cases} A = -\frac{1}{8} \\ B = \frac{9}{4} \\ C = -\frac{1}{2} \\ D = \frac{1}{8} \end{cases}$$

Rule 4

corresponding to any quadratic factor ax^2+bx+c in the denominator, there will be a partial fraction of the form $\frac{Ax+B}{ax^2+bx+c}$

example: $\frac{x^3-2}{x^4-1}$

degree 3 $\rightarrow$ x^3-2 simplify as far as possible

degree 4 $\rightarrow$ x^4-1 make it quadratic

$$\frac{x^3-2}{x^4-1} = \frac{x^3-2}{(x^2+1)(x^2-1)} = \frac{x^3-2}{(x^2+1)(x+1)(x-1)}$$

$$= \frac{Ax+B}{x^2+1} + \frac{C}{x+1} + \frac{D}{x-1}$$

$(A=\frac{1}{2}, B=1, C=\frac{3}{4}, D=-\frac{1}{4})$

Rule 4^a

repeated quadratic factors in the denominator are dealt with in a similar way to repeated linear factors. (see Rule 3 for linear factors)

example: $\frac{x^2+1}{(x^2+x+1)^2}$

degree 2 $\rightarrow$ x^2+1

degree 4 $\rightarrow$ $(x^2+x+1)^2$ (n=2)

$$= \frac{Ax+B}{x^2+x+1} + \frac{Cx+D}{(x^2+x+1)^2}$$

degree 2 $\rightarrow$ x^2+x+1 (n=1)

degree 4 $\rightarrow$ $(x^2+x+1)^2$ (n=1)

"Exercise"

$$\frac{1}{x^2(x-2)} = \frac{A}{x} + \frac{B}{x^2} + \frac{C}{x-2}$$

(from the rules)
how to get A, B, C

multiply both sides by $x^2(x-2)$:

$$1 = Ax(x-2) + B(x-2) + Cx^2$$

"take" $x=0 \Rightarrow B = -\frac{1}{2}$

"take" $x=2 \Rightarrow C = \frac{1}{4}$

comparing coefficients for $x^2 \Rightarrow A+C=0 \Rightarrow A = -\frac{1}{4}$

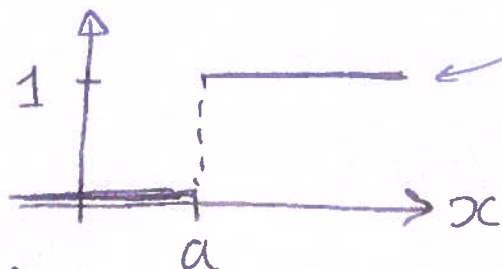
$$1 = Ax^2 - 2Ax + Bx - 2B + Cx^2$$

 extra

(19)

Heaviside function

(unit step function)



$$\mathcal{H}(x-a) = \begin{cases} 0, & x < a \\ 1, & x \geq a \end{cases}$$

check notation

example:

$$\mathcal{H}(x-a) \cdot f(x-a) = \begin{cases} 0, & x < a \text{ (because } \mathcal{H}=0) \\ f(x-a), & x \geq a \text{ (because } \mathcal{H}=1) \end{cases}$$

f : "signal", then : "same signal" with a "delay" of x

property

$$\mathcal{L}(\mathcal{H}(x-a)f(x-a))(s) = e^{-as} \cdot F(s)$$

$\underbrace{\quad}_{= \mathcal{L}(f(x))}(s)$

Convolution
(remember)

$$f * g(x) = \int_0^x f(x-\bar{x}) g(\bar{x}) d\bar{x}$$

but now different
slightly

instead of

$\int_{-\infty}^{\infty}$ as in Fourier-transform

Property:

$$\mathcal{L}(f * g) = \mathcal{L}(f) \cdot \mathcal{L}(g)$$



Voorbeeld 1

A

$$\begin{cases} y' + 2y = 3 \\ y(0) = 5 \end{cases}$$

Laplace

transformatie $\Rightarrow sY(s) - y(0) + 2Y(s) = \frac{3}{s}$

invullen
&
herschrijven

$$(s+2)Y(s) = \frac{3}{s} + 5$$

$$Y(s) = \frac{3}{s(s+2)} + \frac{5}{s+2}$$

$$= 3 \left[\frac{A}{s} + \frac{B}{s+2} \right] + 5 \cdot \frac{1}{s+2}$$

$$= 3 \left[\frac{A(s+2) + Bs}{s(s+2)} \right] + 5 \cdot \frac{1}{s+2}$$

$$\begin{aligned} \Rightarrow (A+B)s + 2A &\stackrel{\text{moet}}{=} 1 \\ A+B &= 0 \\ A = 1/2, B &= -1/2 \end{aligned}$$

$$= 3 \cdot \frac{1}{2} \cdot \frac{1}{s} - 3 \cdot \frac{1}{2} \cdot \frac{1}{s+2} + 5 \cdot \frac{1}{s+2}$$

$$= \frac{3}{2} \cdot \frac{1}{s} + \frac{7}{2} \cdot \frac{1}{s+2}$$

$$\Rightarrow y(t) = \frac{3}{2} + \frac{7}{2} e^{-2t}$$

check: $y' = -7e^{-2t}$

$$y' + 2y = \cancel{-7e^{-2t}} + 3 + \cancel{7e^{-2t}} = 3 \quad \text{✓}$$

$$y(0) = \frac{3}{2} + \frac{7}{2} = \frac{10}{2} = 5 \quad \text{✓}$$

voorbeeld 2

$$\begin{cases} y' + 3y = e^{2t} \\ y(0) = 1 \end{cases}$$

B

$$\mathcal{L}(y' + 3y) = s Y(s) - y(0) + 3 Y(s) = (s+3) Y(s) - 1$$

$$\mathcal{L}(e^{2t}) = \frac{1}{s-2}$$

$$\Rightarrow (s+3) Y(s) - 1 = \frac{1}{s-2}$$

$$\Rightarrow Y(s) = \frac{1}{s+3} + \frac{1}{(s-2)(s+3)}$$

kruislings
vermenigvuldigen

schrijf als $\left\{ \frac{A}{s-2} + \frac{B}{s+3} \right\}$

$$= \frac{A(s+3) + B(s-2)}{(s-2)(s+3)}$$

moet gelden

$$\Rightarrow 1 = A(s+3) + B(s-2)$$

$$\text{dwz } 1 = (A+B)s + 3A - 2B$$

$$\Rightarrow \begin{cases} A+B=0, & B=-A \\ 3A-2B=1 \end{cases} \iff 3A+2A=1$$

$$5A=1$$

$$A = 1/5$$

$$\text{en } B = -1/5$$

$$\rightarrow Y(s) = \frac{1}{s+3} + \frac{1}{5} \cdot \frac{1}{s-2} - \frac{1}{5} \cdot \frac{1}{s+3}$$

neem inverse
Laplace
(check tabel)

$$\Rightarrow y(t) = \frac{4}{5} \cdot e^{-3t} + \frac{1}{5} e^{2t}$$

check: $y' = -\frac{12}{5} e^{-3t} + \frac{2}{5} e^{2t}$

$$3y = \frac{12}{5} e^{-3t} + \frac{3}{5} e^{2t}$$
$$y' + 3y = \frac{2}{5} e^{2t} = e^{2t}$$
$$y(0) = \frac{4}{5} + \frac{1}{5} = 1$$

woodveld 3

$$\begin{cases} y'' + 4y = 0 \\ y(0) = 1, y'(0) = 3 \end{cases}$$

C

Laplace
transformatie
 $\Rightarrow$

$$s^2 Y(s) - \underbrace{s y(0)}_{=1} - \underbrace{y'(0)}_{=3} + 4 Y(s) = 0$$

$$\Rightarrow Y(s) = \frac{1}{s^2 + 4} + \frac{3}{s^2 + 4} = \frac{3}{2} \cdot \frac{2}{s^2 + 2^2}$$

check
tabel
("neem inverse
Laplace
transformatie")

$$\Rightarrow y(t) = \cos(2t) + \frac{3}{2} \sin(2t)$$

check (inverse) $\Rightarrow$ f

extra om de oefening

$$\begin{cases} y'' + 2y' + 5y = 0 \\ y(0) = 1, y'(0) = 0 \end{cases}$$

(zie webpagina)

$$\begin{cases} y'' - 10y' + 9y = 5t \\ y(0) = -1, y'(0) = 2 \end{cases}$$

(" " " ")

$\rightarrow$ 1^e vraaguur!

algemeen

$$\begin{cases} y'' + c_1 y' + c_2 y = c_3 \\ y(0) = A, y'(0) = B \end{cases}$$

constante
(special
geval)

$\begin{matrix} c_1 \\ c_2 \\ c_3 \\ A \\ B \end{matrix} \left. \vphantom{\begin{matrix} c_1 \\ c_2 \\ c_3 \\ A \\ B \end{matrix}} \right\} \text{gegeven}$

D

$$\begin{aligned} &\Downarrow \\ &\left[s^2 Y(s) - \overset{=A}{s y(0)} - \overset{=B}{y'(0)} \right] \\ &\quad + c_1 \left[s Y(s) - \overset{=A}{y(0)} \right] \\ &\quad + c_2 \cdot [Y(s)] \\ &\quad \quad \quad = \frac{c_3}{s} \end{aligned}$$

$\Downarrow$

$$(s^2 + c_1 s + c_2) Y(s) = \frac{c_3}{s} + sA + B + c_1 A$$

$$Y(s) = \frac{c_3}{s(s^2 + c_1 s + c_2)} + \frac{sA}{s^2 + c_1 s + c_2} + \frac{B + c_1 A}{s^2 + c_1 s + c_2}$$

“breuksplitsen”

$$\dots \rightarrow Y(s) = \dots$$

$\Downarrow$ inverse toepassen
Laplace (tabel gebruiken)

$$y(t) = \dots$$